



# Isotropic FWI

## NZ 3D Processing

28 October 2020

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INSTITUTE FOR GEOPHYSICS



Passion for Geoscience

- **Objective:**

To QC isotropic (ISO) FWI result.

- **Procedure:**

Isotropic FWI was run with both streamer and OBS data from 2.5 Hz to 7Hz. Only refraction energy is used in the velocity inversion. For OBS data, a mute is applied to exclude the data that is affected by the recording issue.

To evaluate the result, a depth migration volume was generated using data after low cut filter.

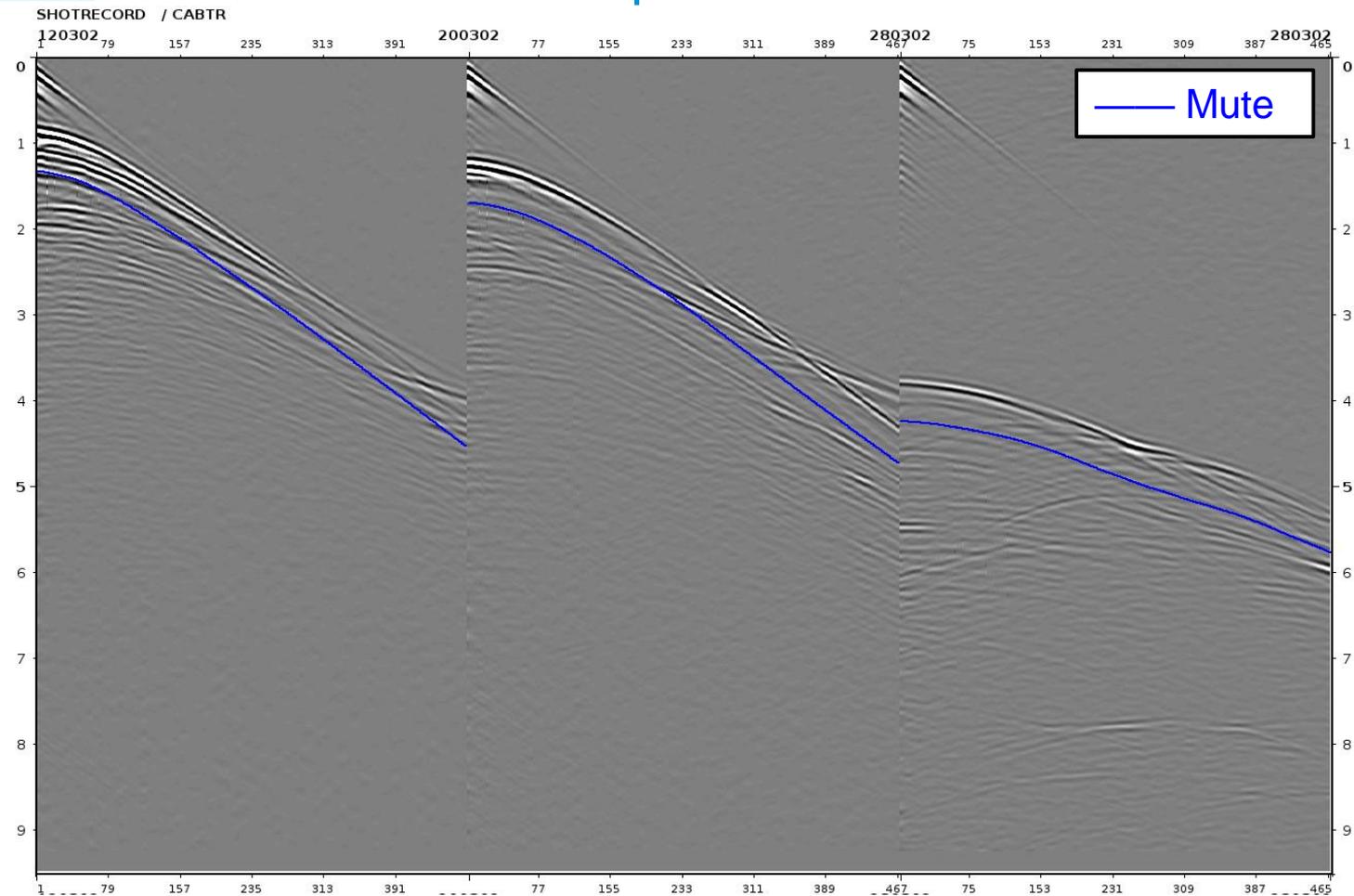
- **Display:**

Velocity and FWI synthetic.

- **Observation and Recommendation:**

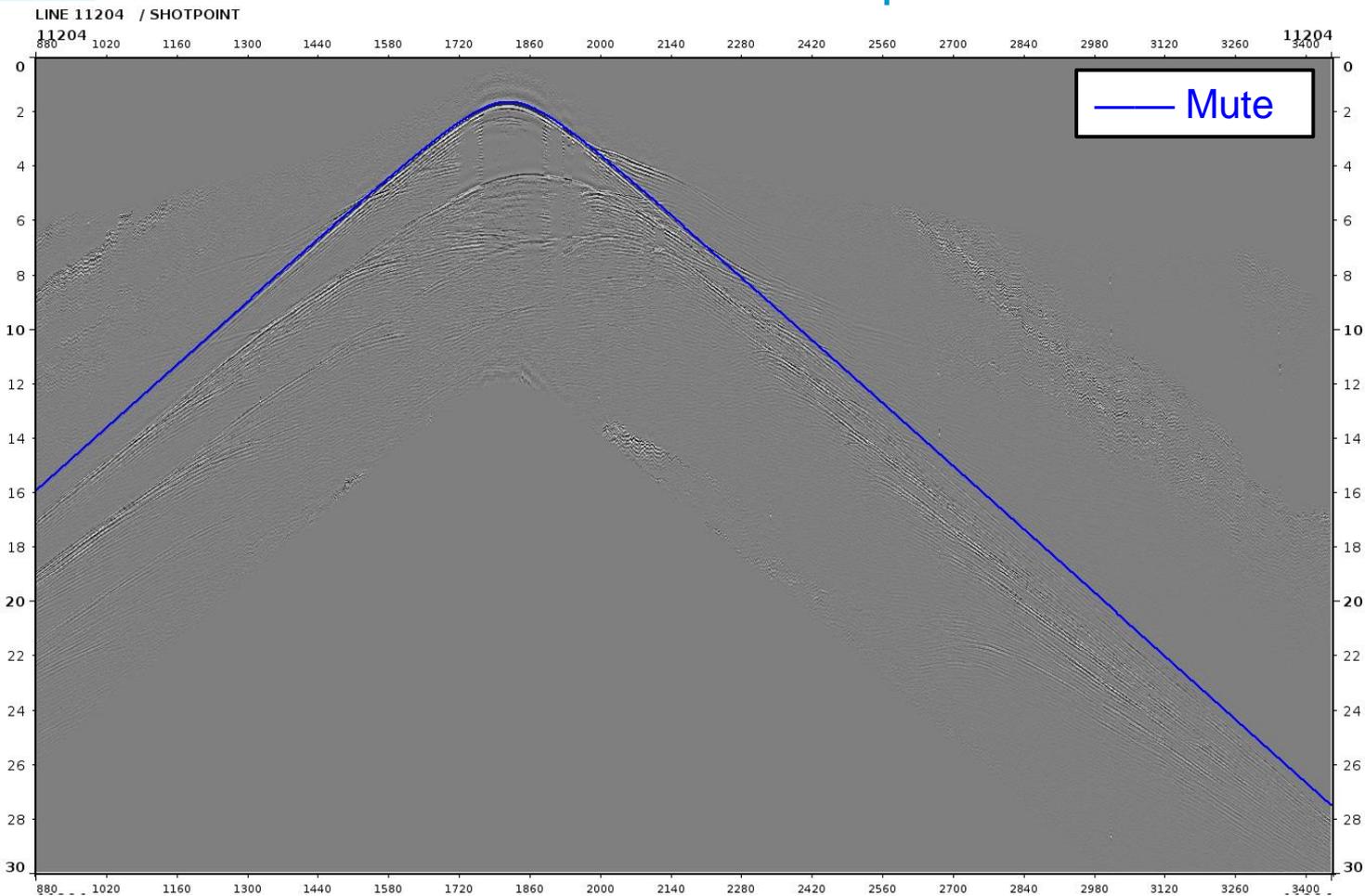
Current ISO FWI gives reasonable update down to ~2km beneath Water Bottom (WB). Velocity updated deeper than this depth is hard to be evaluated at the moment, due to interference of multiples. We're working on a VMB depth migration volume with major preprocessing steps applied (de-ghost and de-multiple), so we can evaluate the ISO fwi model and proceed to ISO tomography before building TTI model and TTI FWI.

# Streamer 001: FWI Input



- The reflection energy (below the blue line) is muted.

# OBS Node 058: Mute on FWI Input

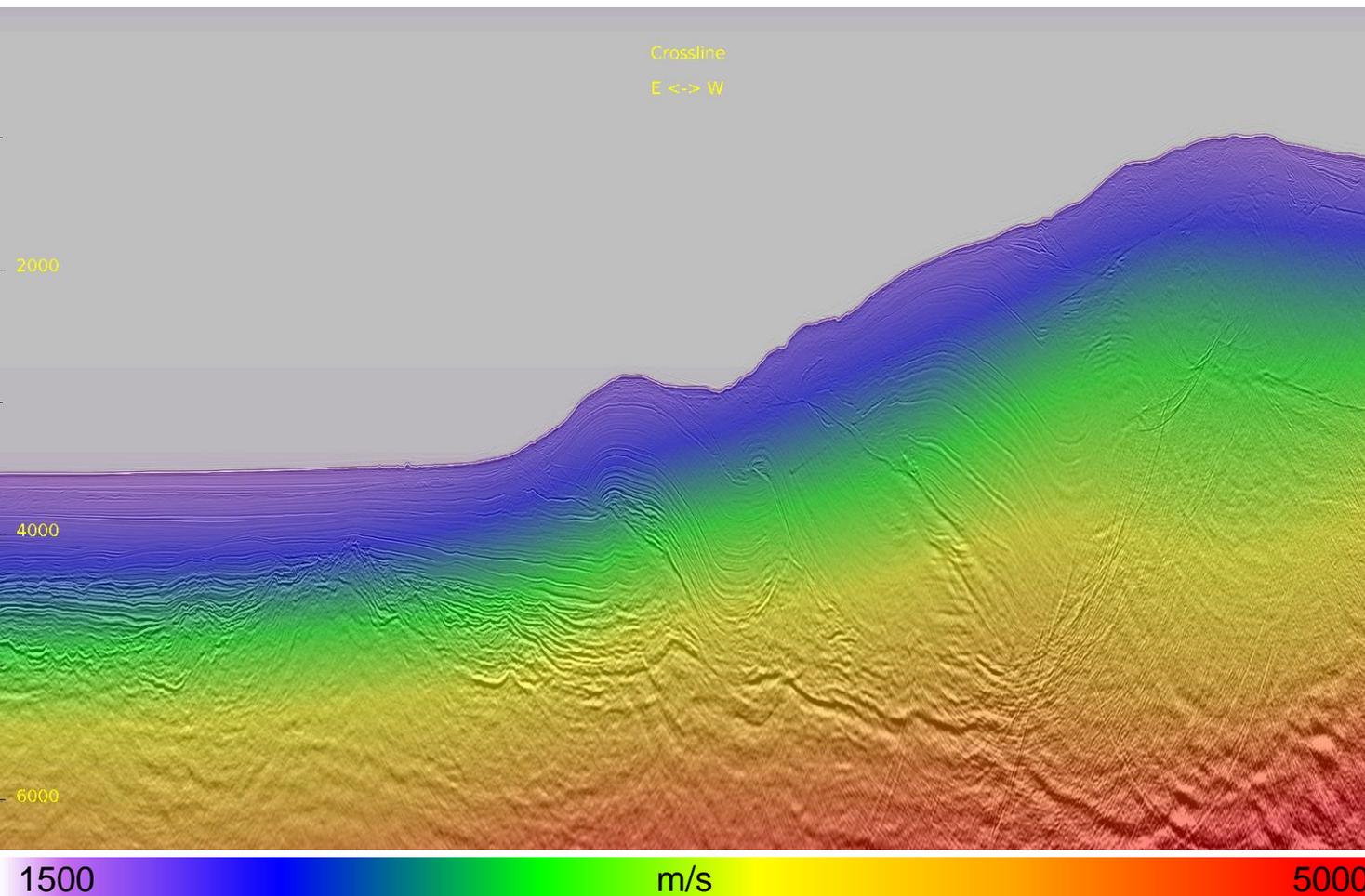


- The reflection energy (below the blue line) is muted, where recording issue happens when amplitudes are high.

# Velocity Model

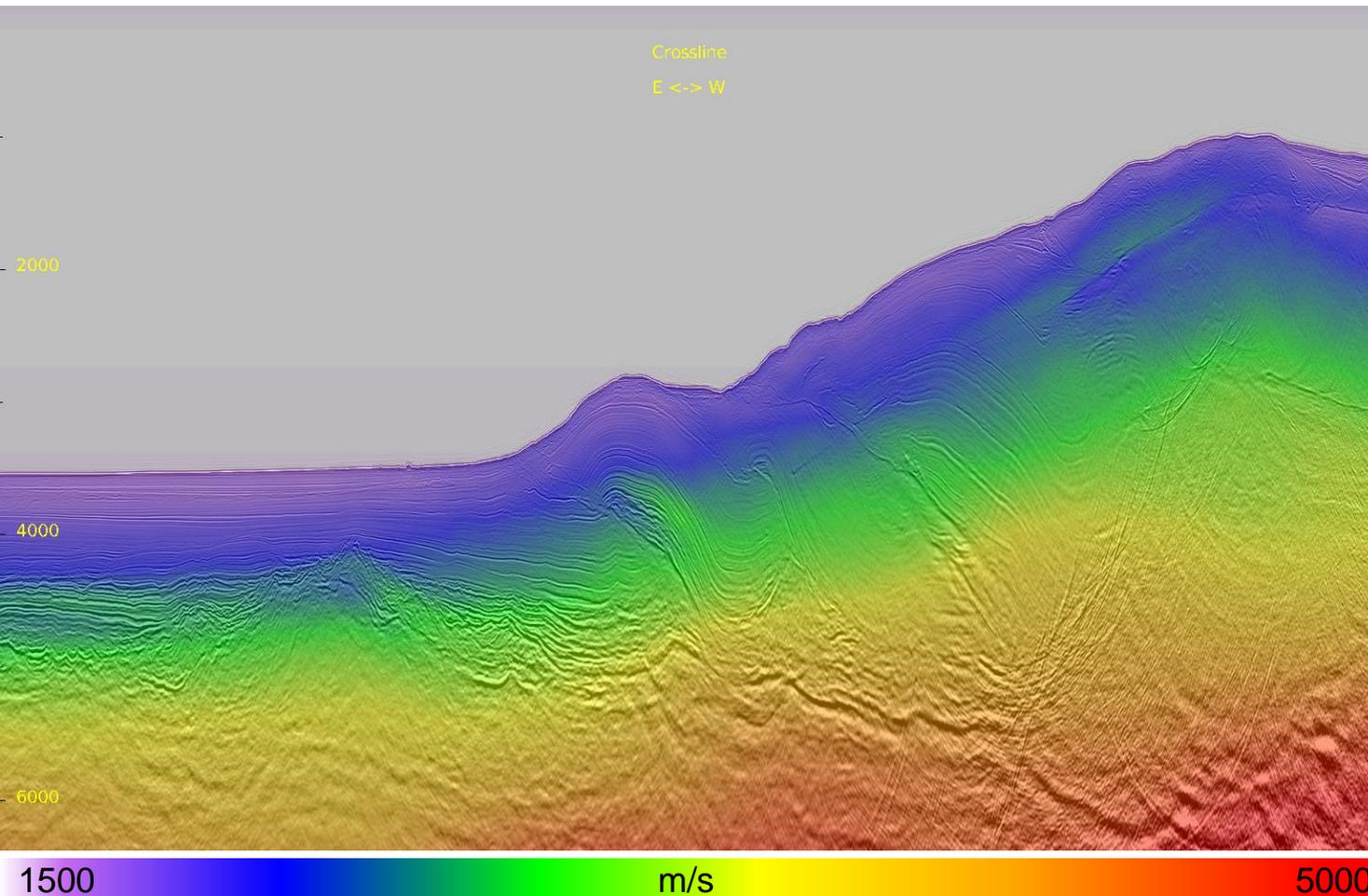


# Inline 436 East: Initial Velocity

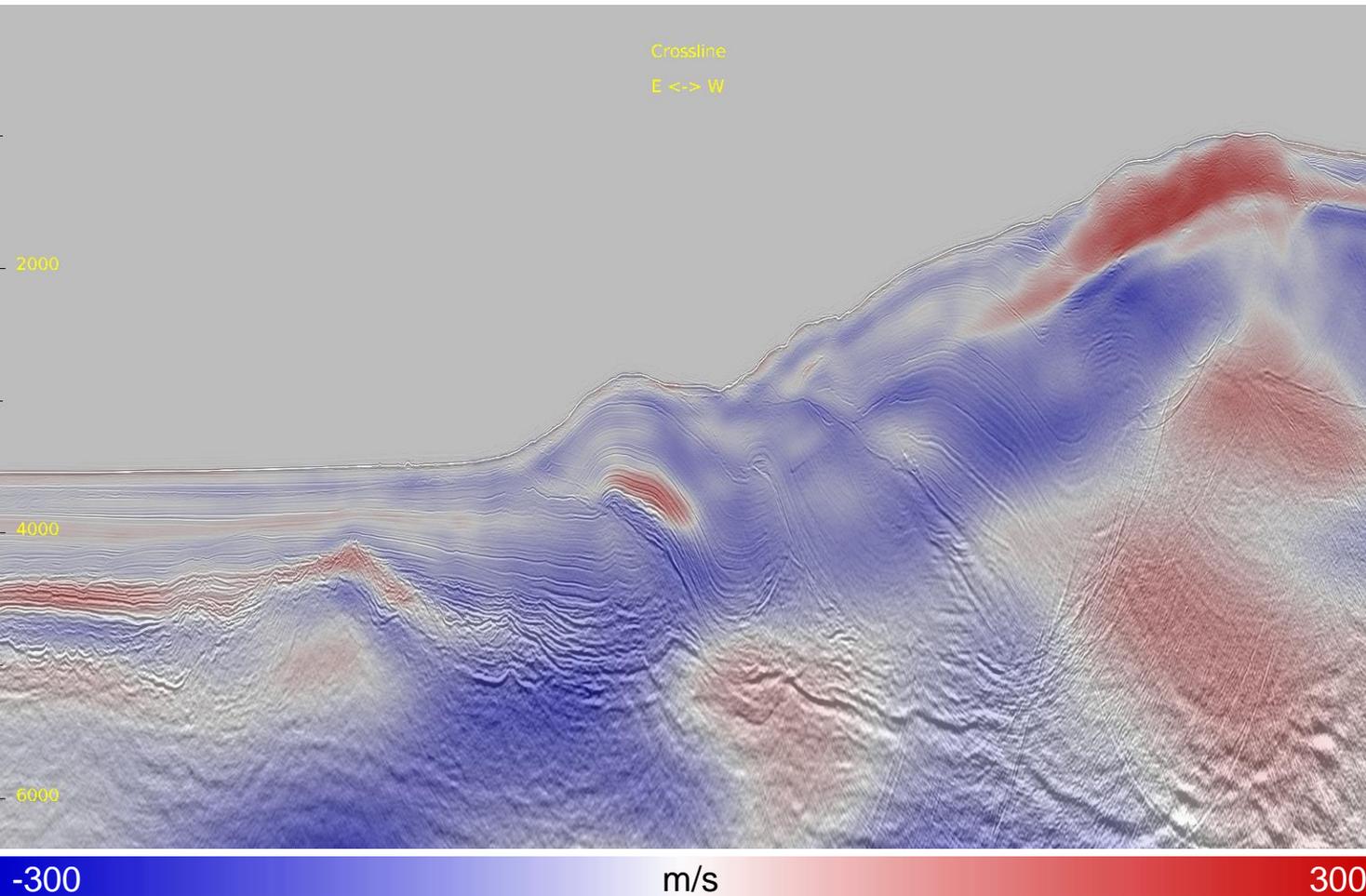


- Initial velocity is smooth.

# Inline 436 East: ISO FWI Velocity

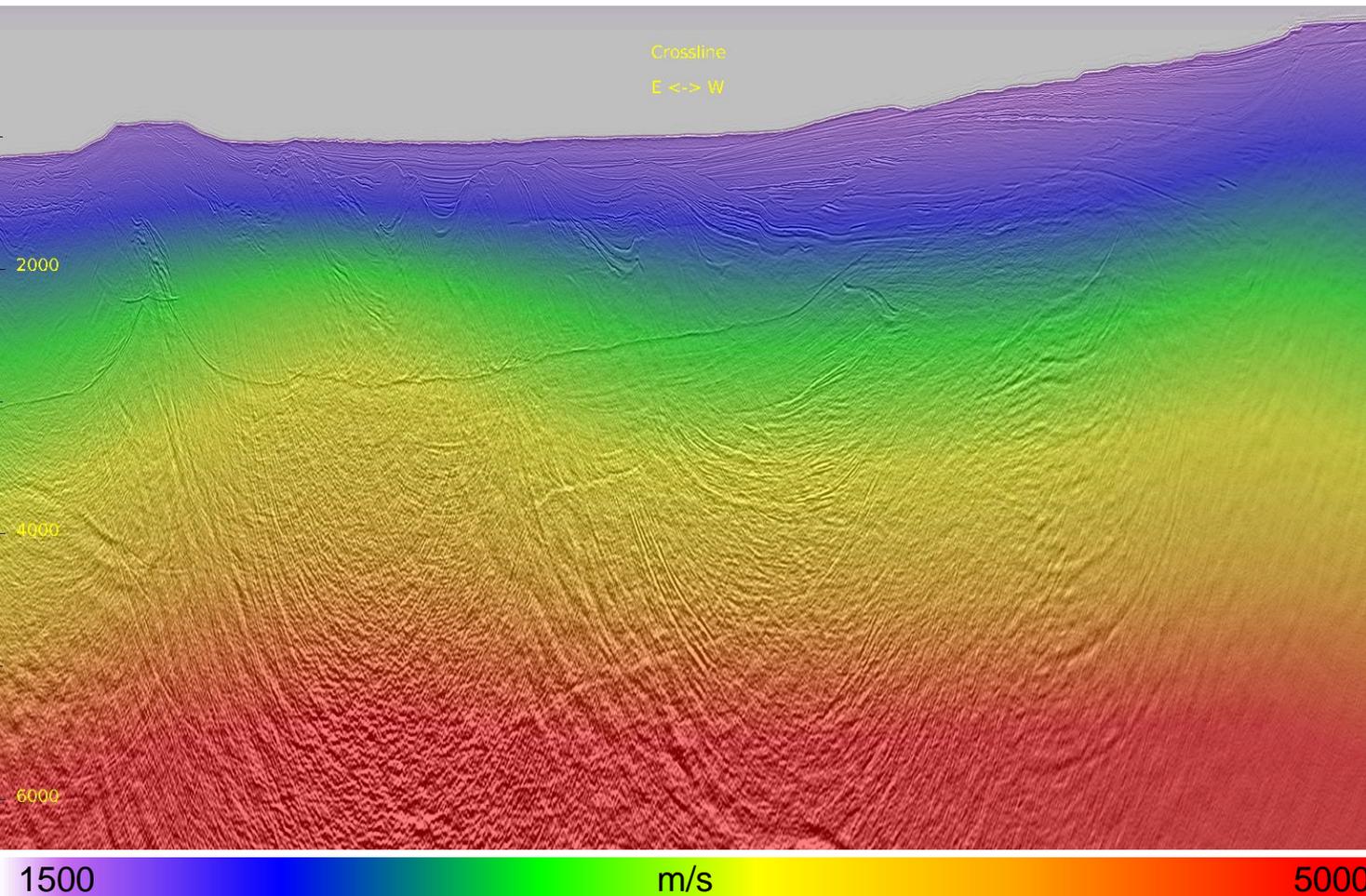


- ISO FWI gives reasonable update that follows geology, down to 2km beneath water bottom.



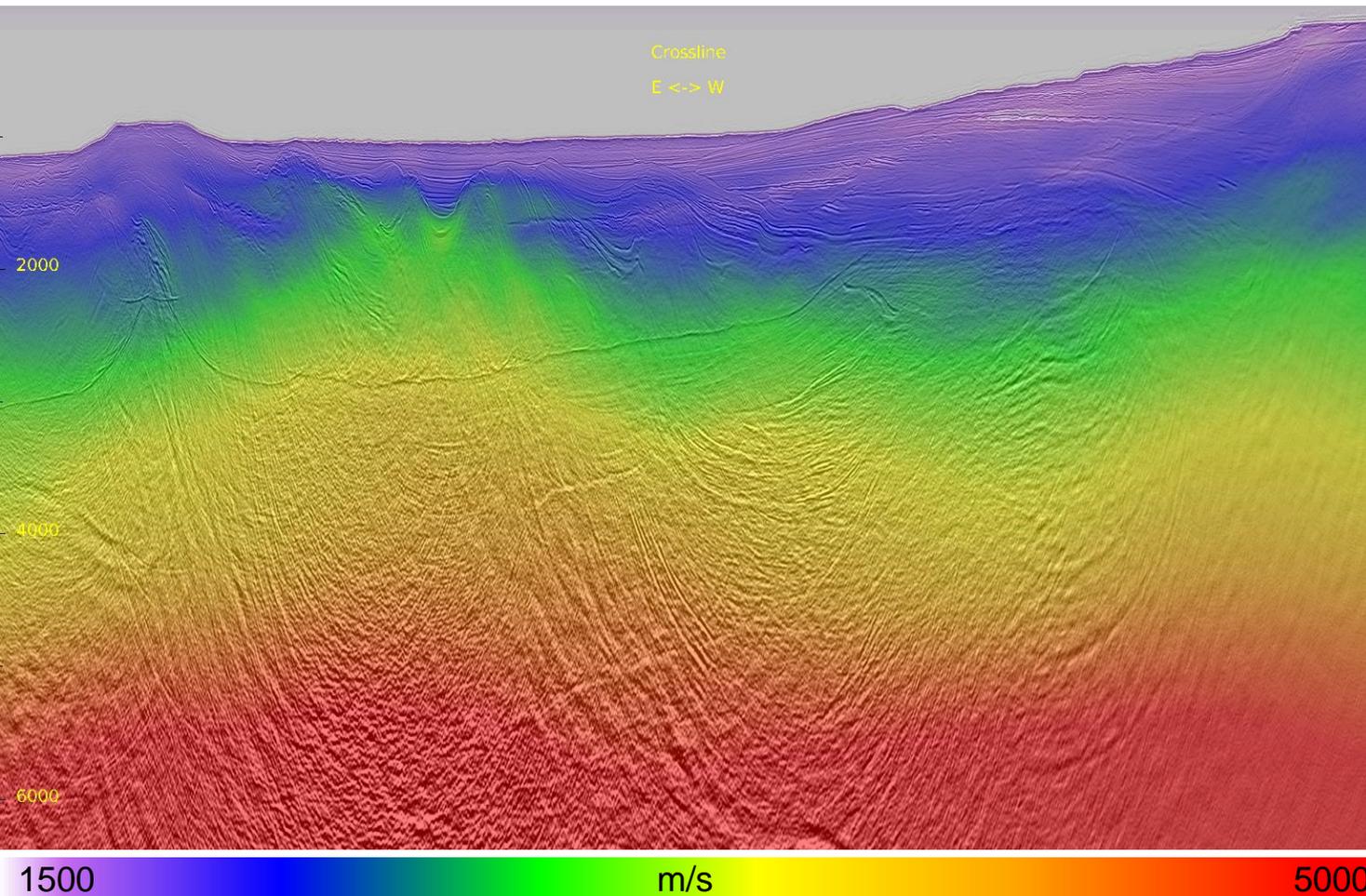
- ISO FWI gives reasonable update that follows geology, down to 2km beneath water bottom.
- The perturbation deeper than 2km beneath water bottom is hard to be assessed, due to interference of multiples on seismic data.

# Inline 436 West: Initial Velocity

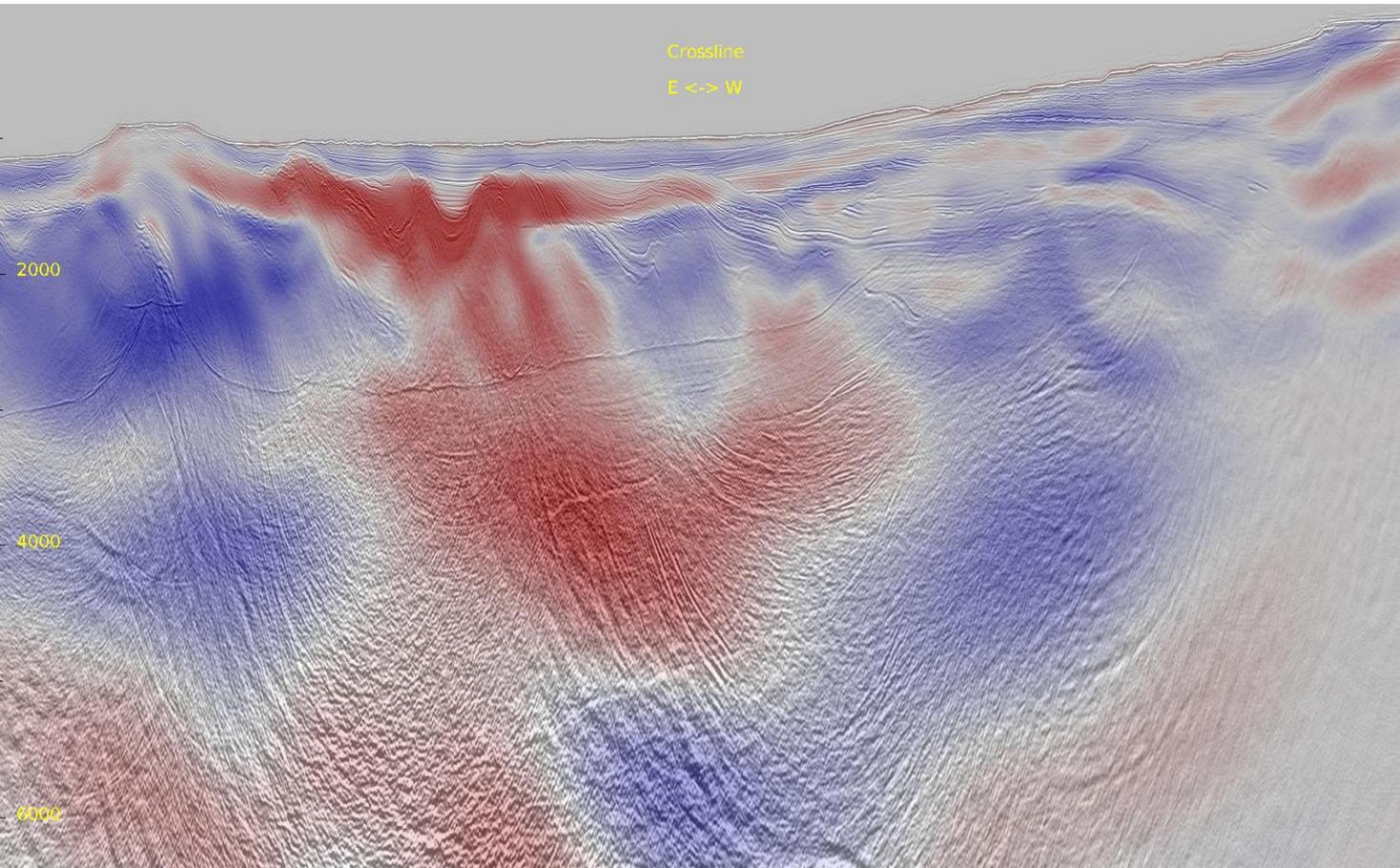


- Initial velocity is smooth.

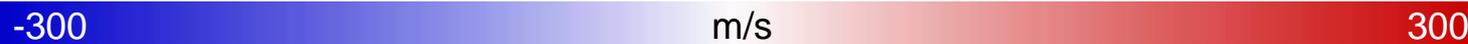
# Inline 436 West: ISO FWI Velocity



- ISO FWI gives reasonable update that follows geology, down to 2km beneath water bottom.



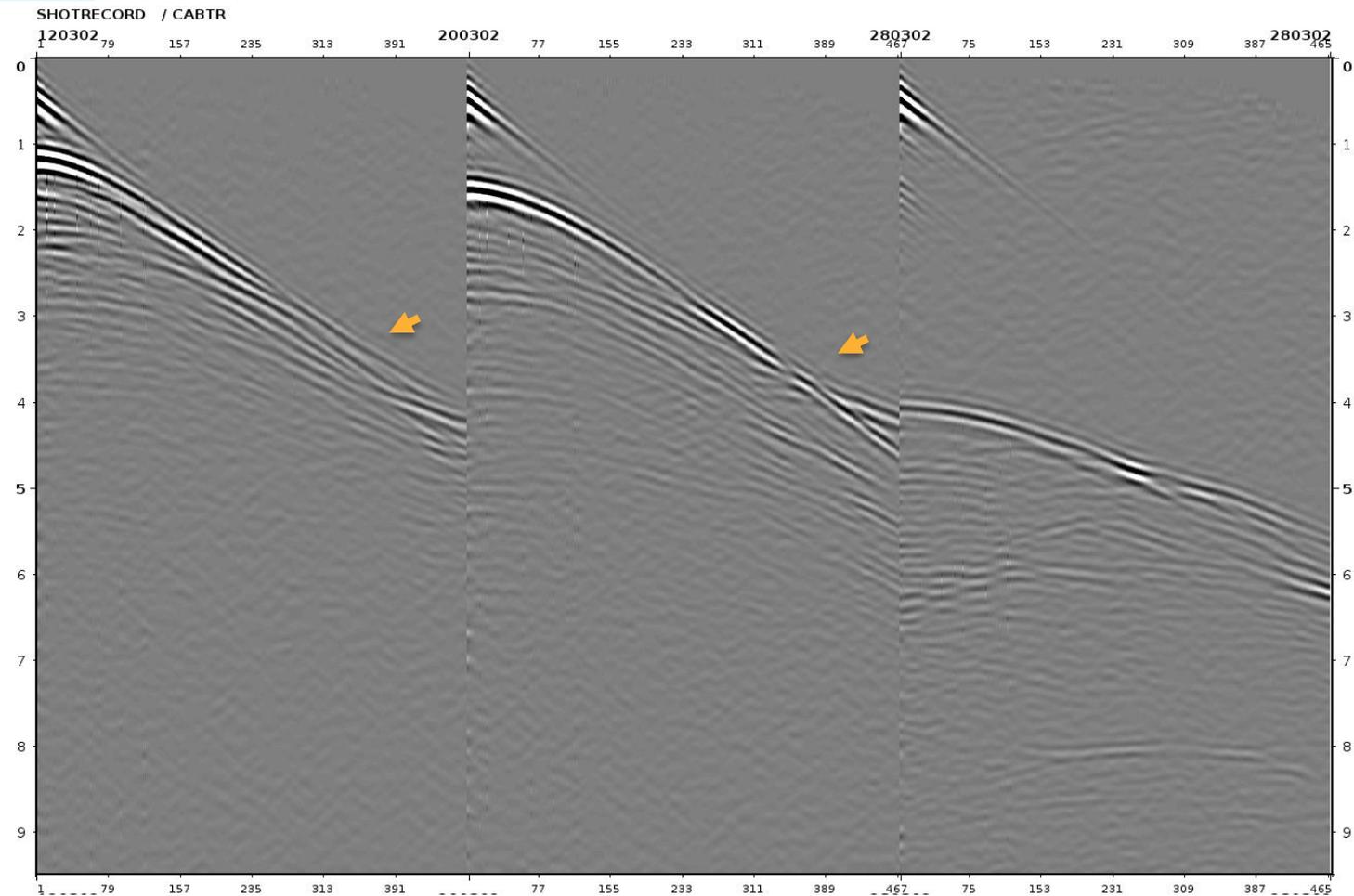
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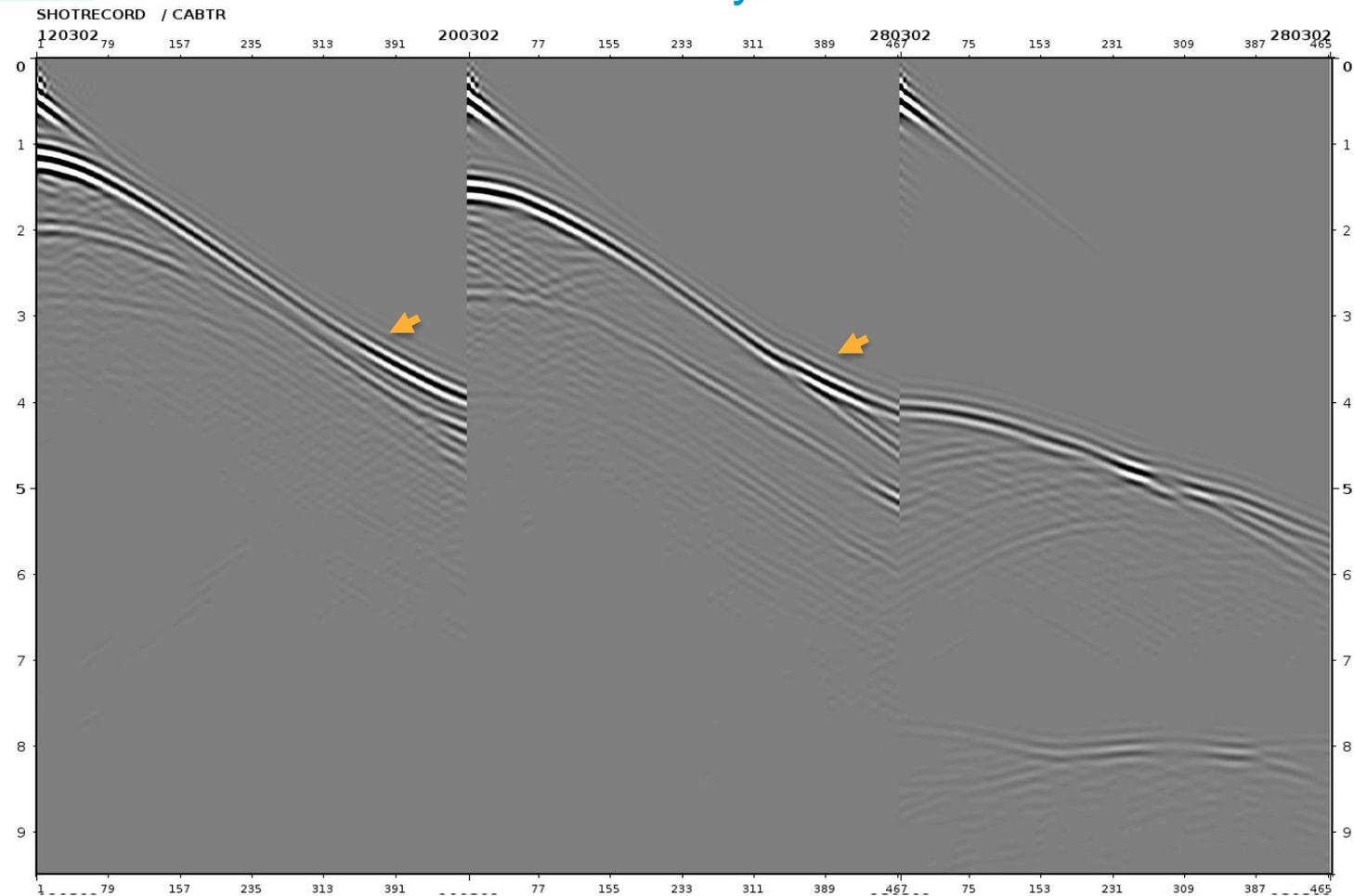
# FWI Synthetic VS Real Data Streamer ( < 7 Hz)



# Streamer 001: Real Shots



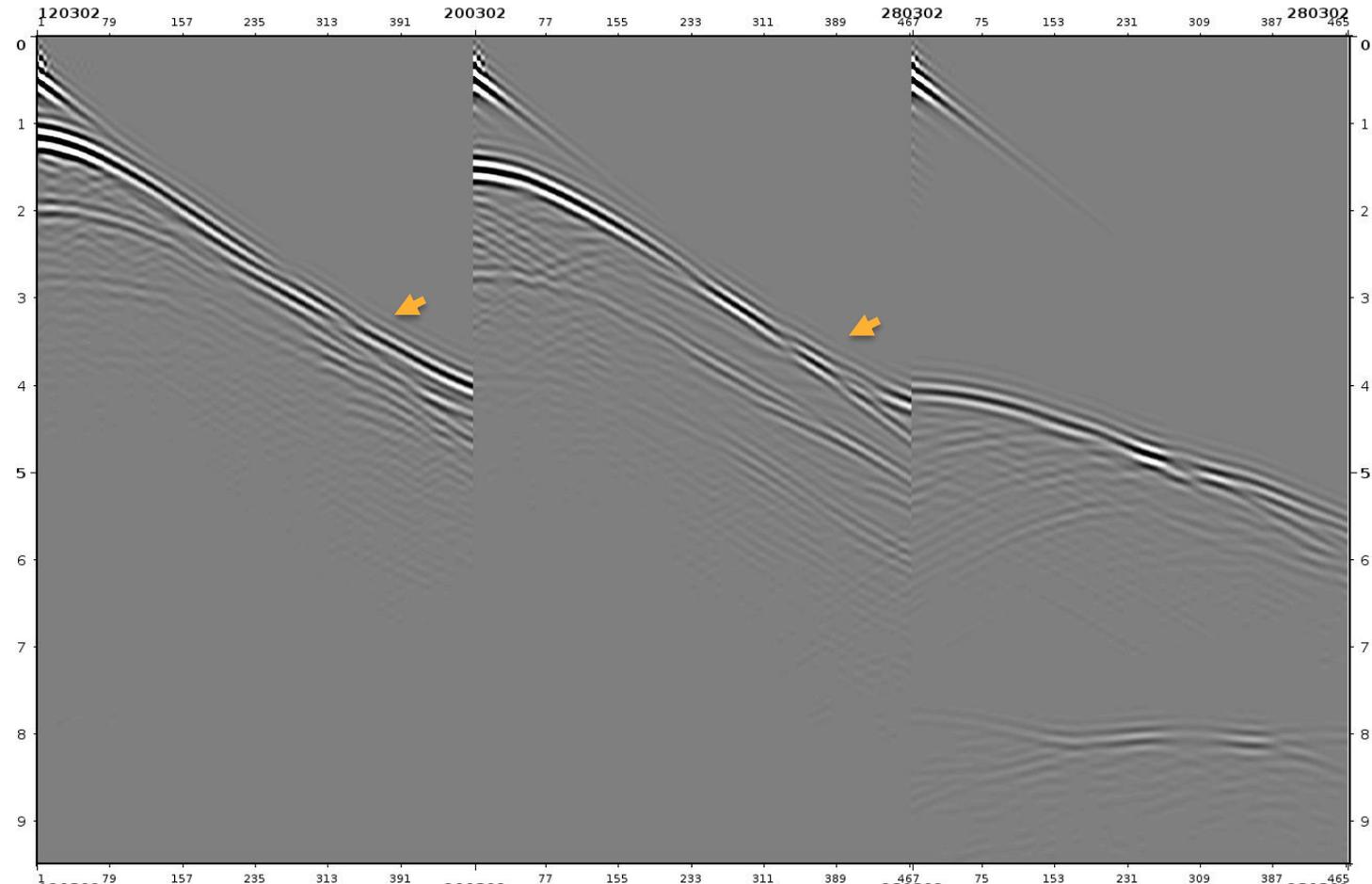
- With initial velocity, synthetic shot and real data matches not very well from mid to far channels.



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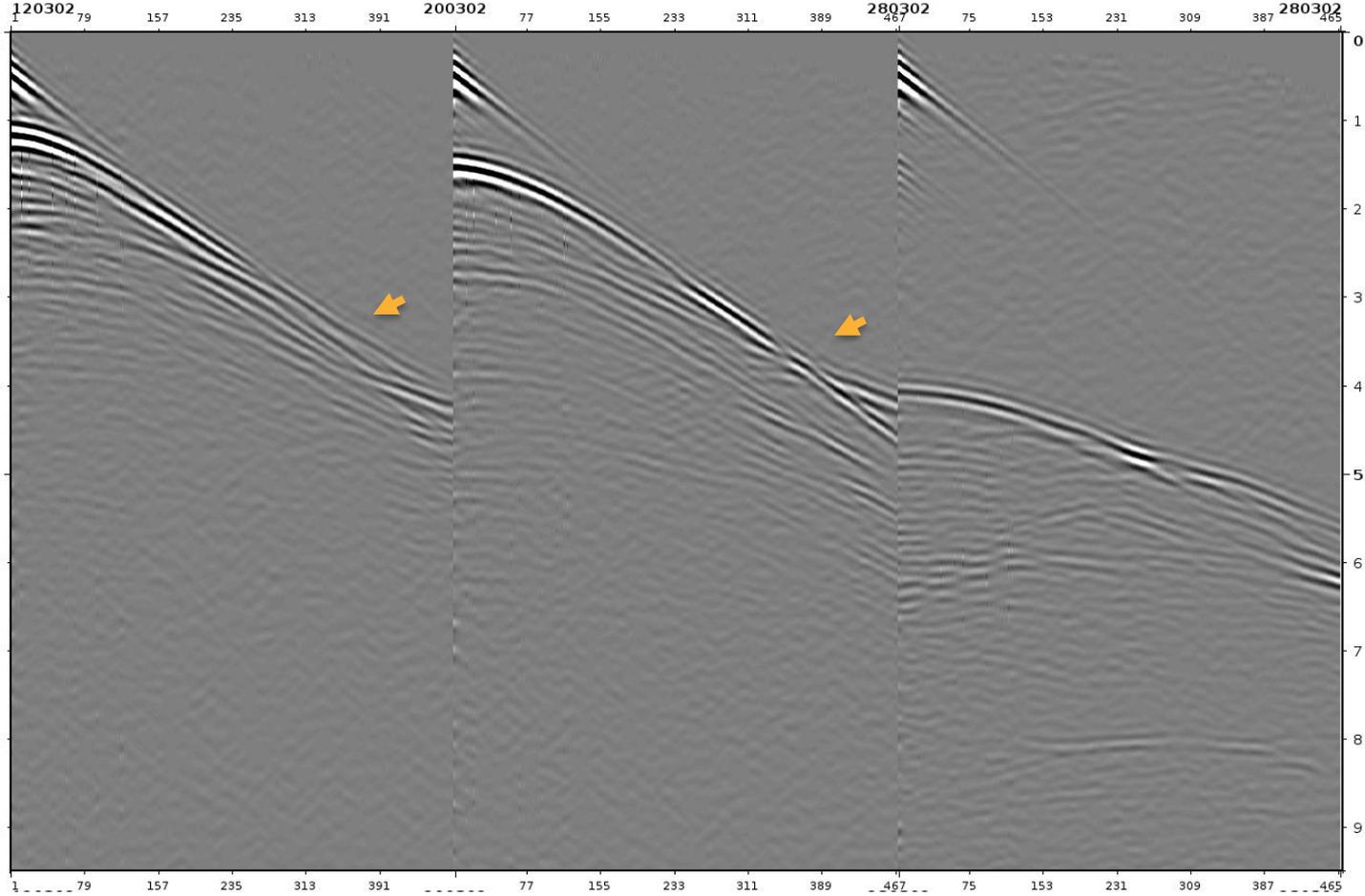
SHOTRECORD / CABTR



- After ISO FWI date, synthetic shots and real data matches better through out all channels.



SHOTRECORD / CABTR



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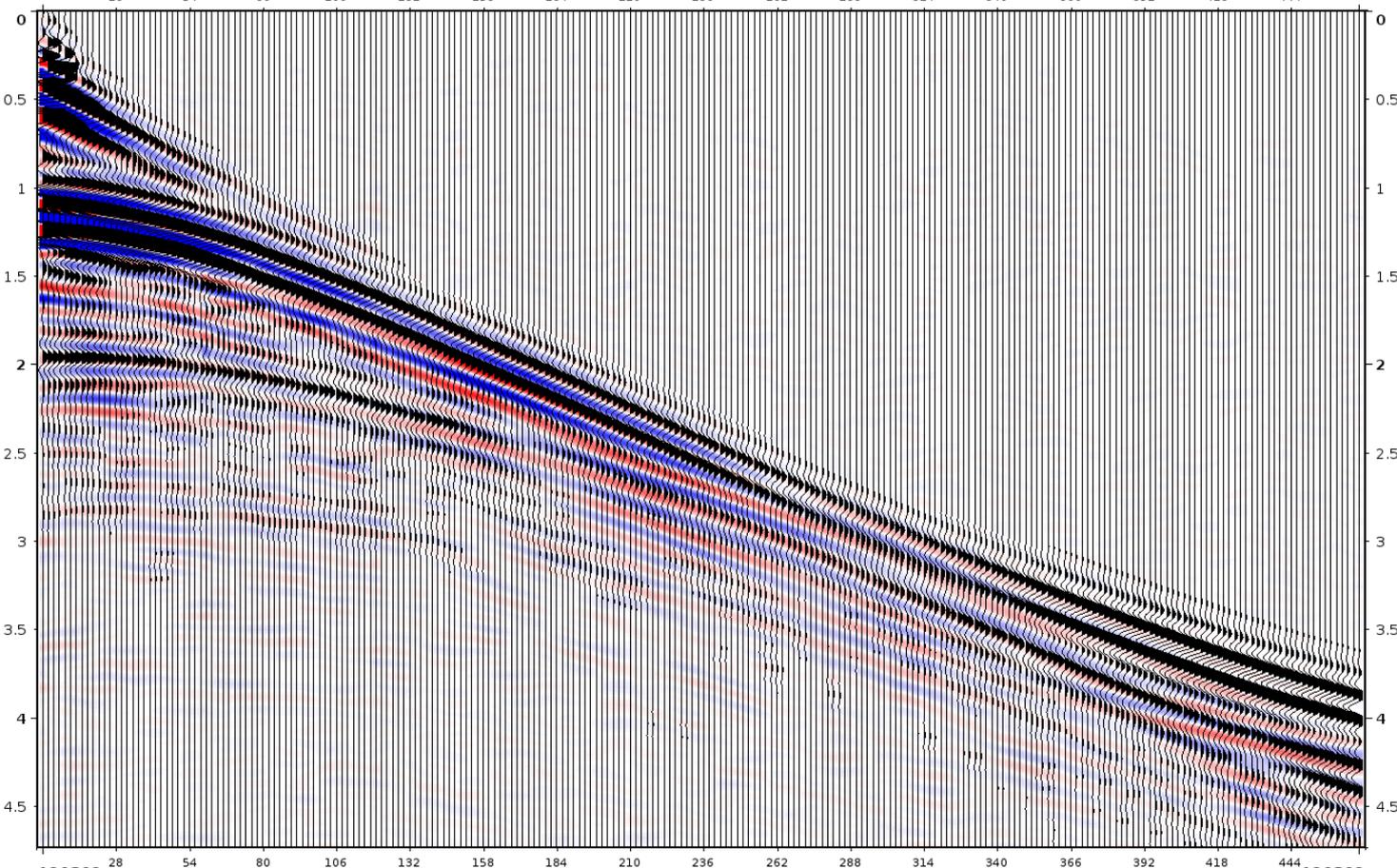


# Streamer 001 Synthetic Overlaid on Real: Initial Velocity

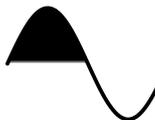
SHOTRECORD 120302 / CABTR

120302

120302



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 Synthetic

 Real

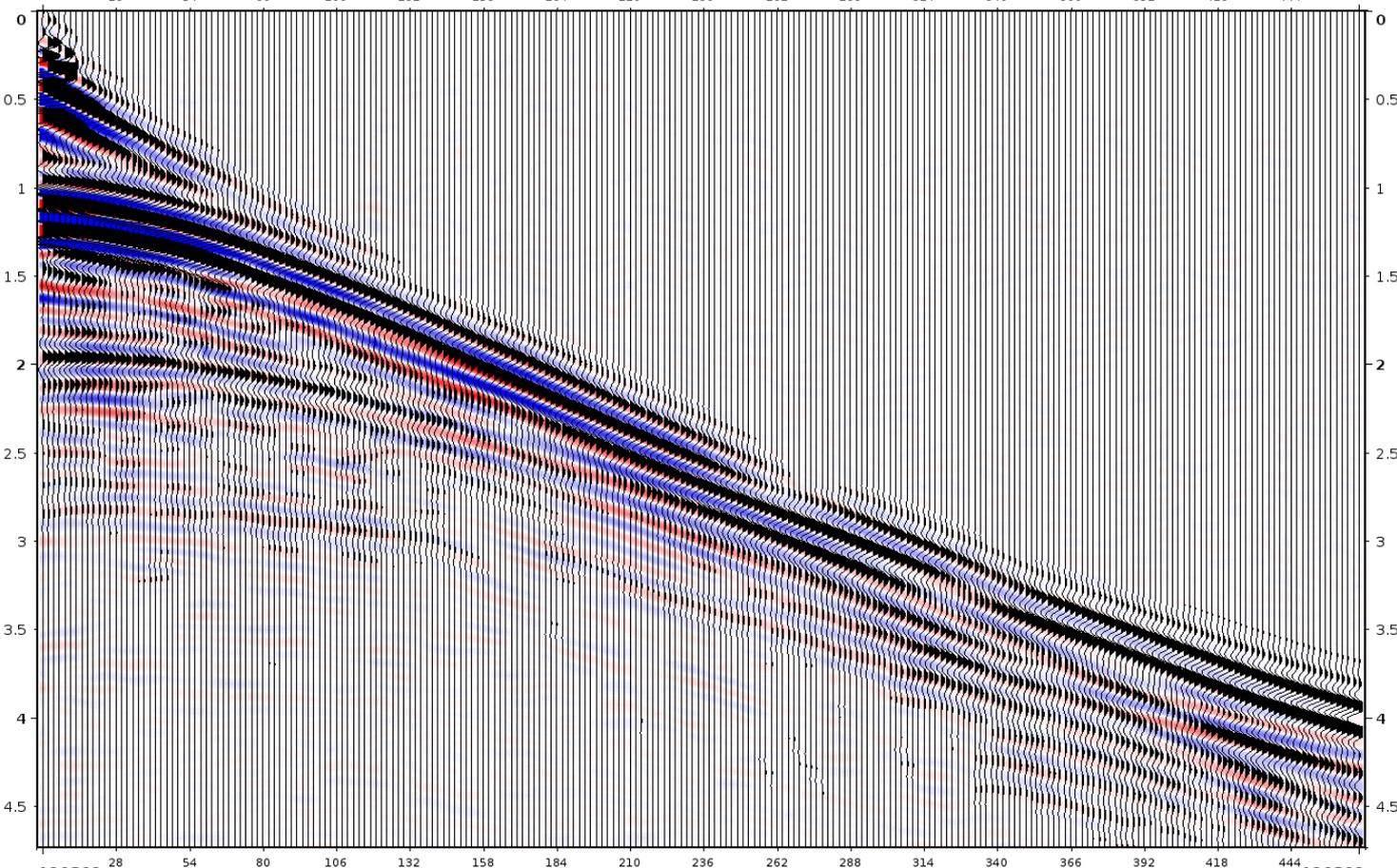


# Streamer 001 Synthetic Overlaid on Real: ISO FWI Velocity

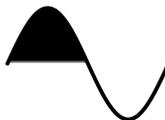
SHOTRECORD 120302 / CABTR

120302

120302



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 Synthetic

 Real

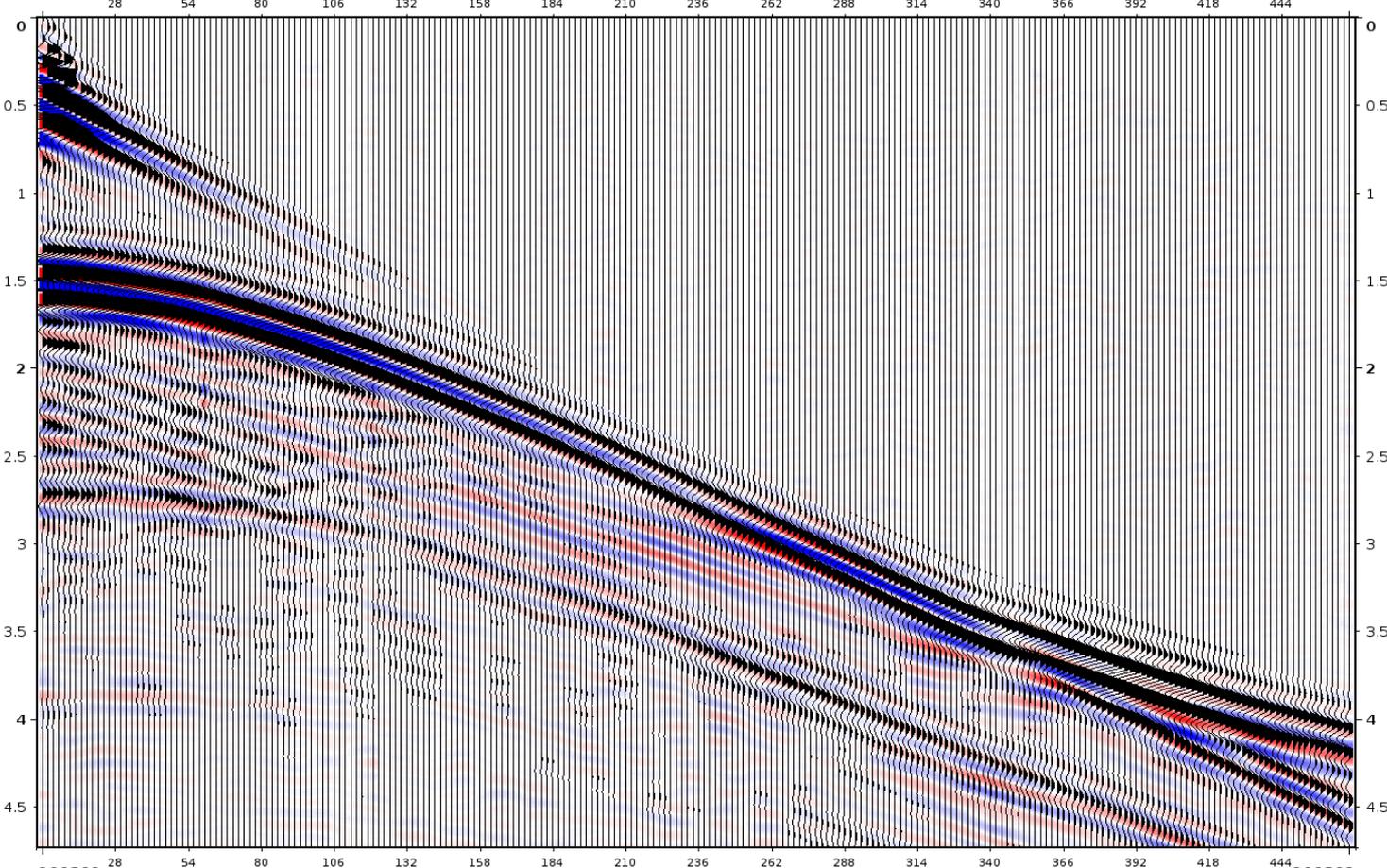


# Streamer 001 Synthetic Overlaid on Real: Initial Velocity

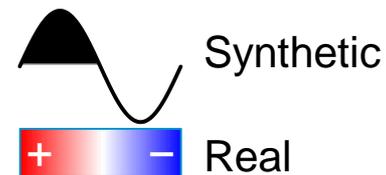
SHOTRECORD 200302 / CABTR

200302

200302



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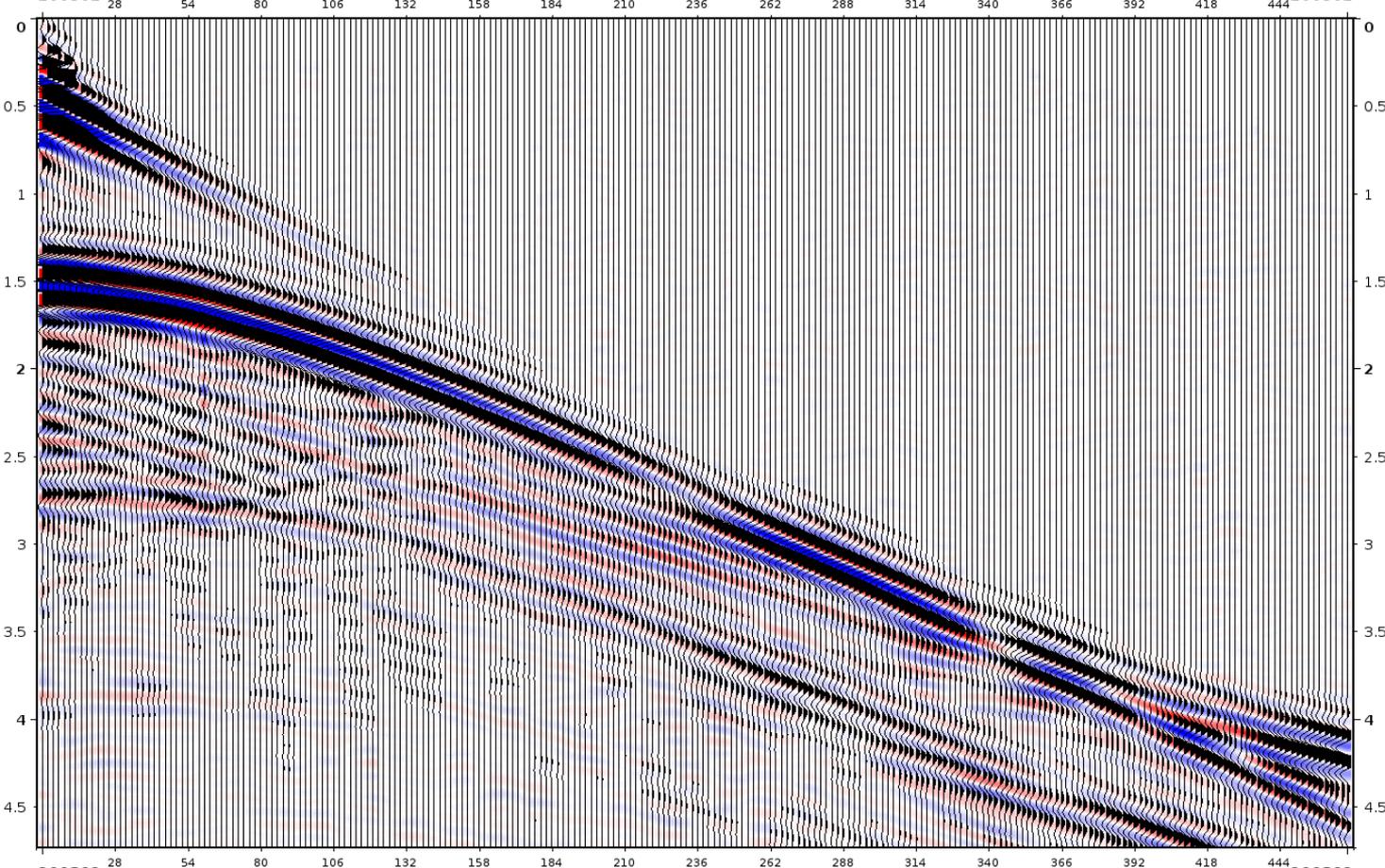


# Streamer 001 Synthetic Overlaid on Real: ISO FWI Velocity

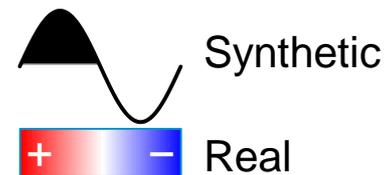
SHOTRECORD 200302 / CABTR

200302

200302

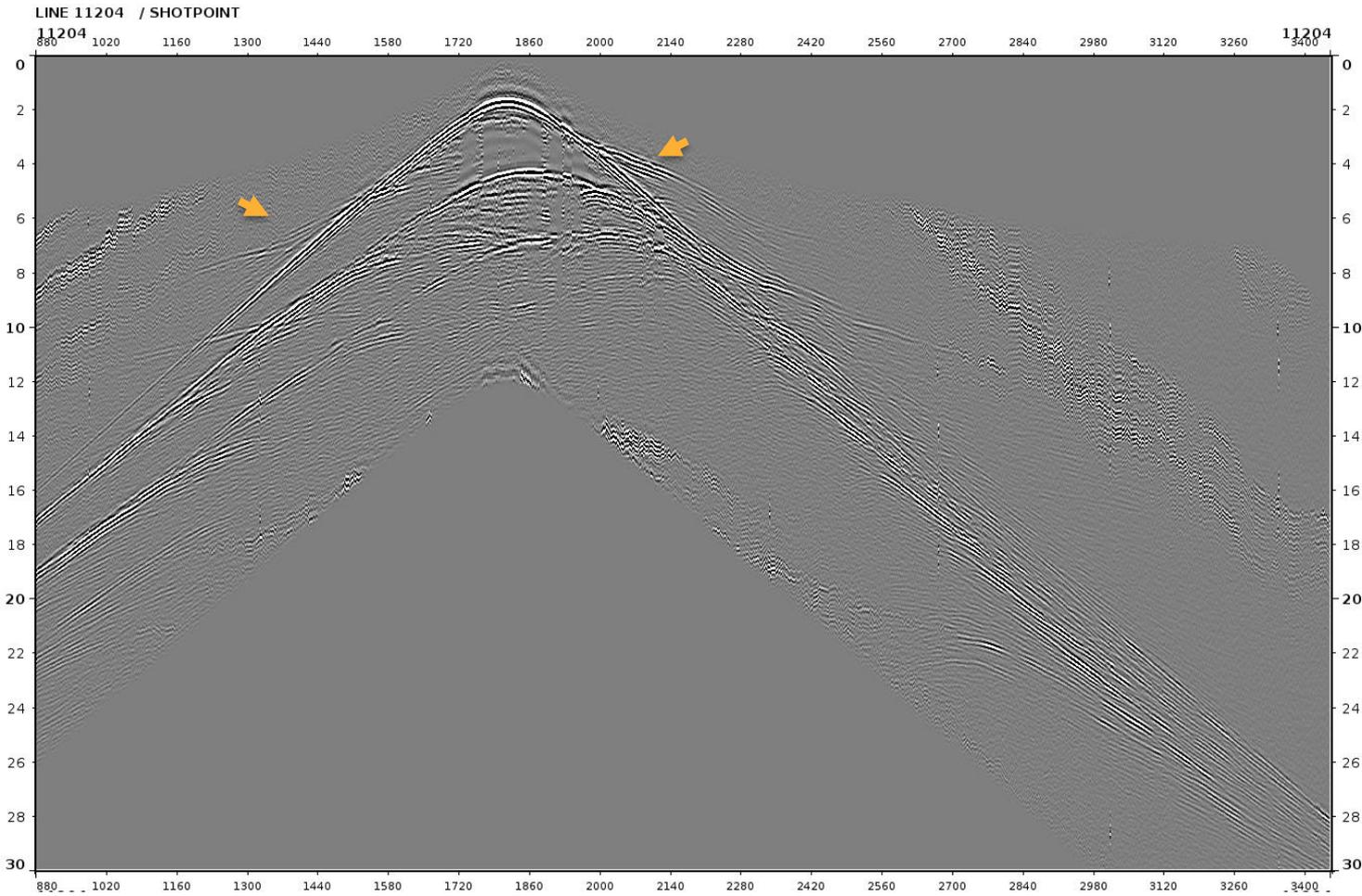


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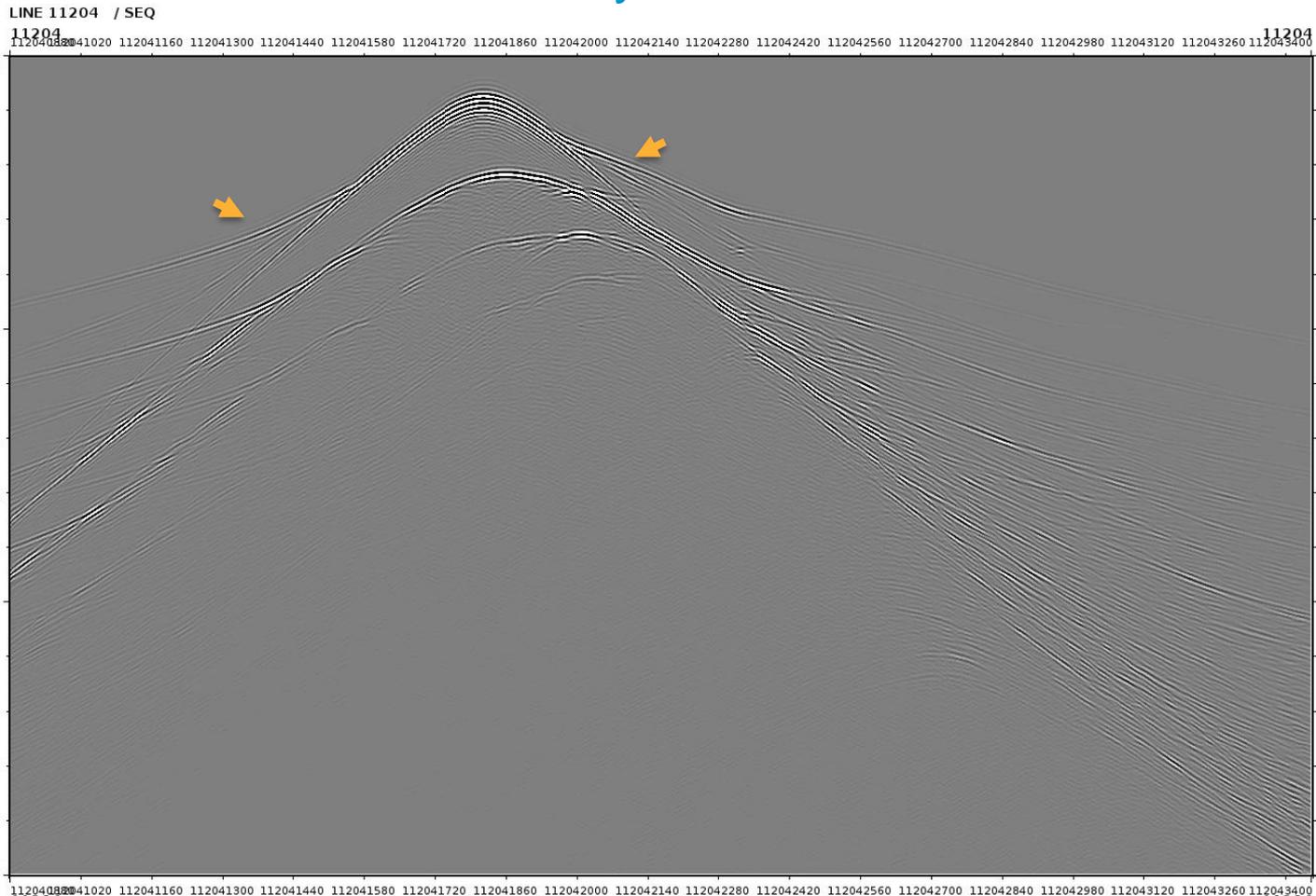


# FWI Synthetic VS Real Data OBS

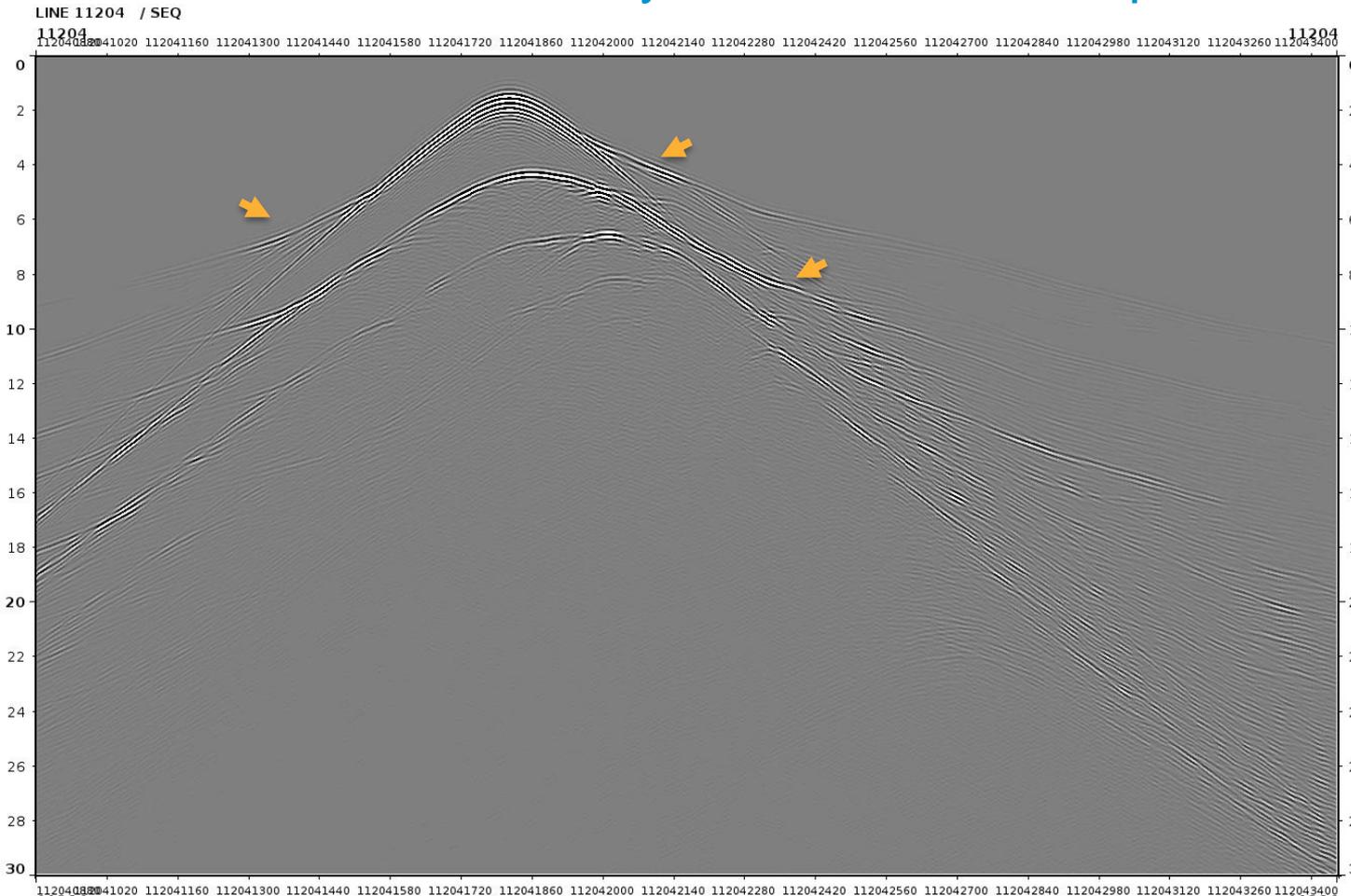




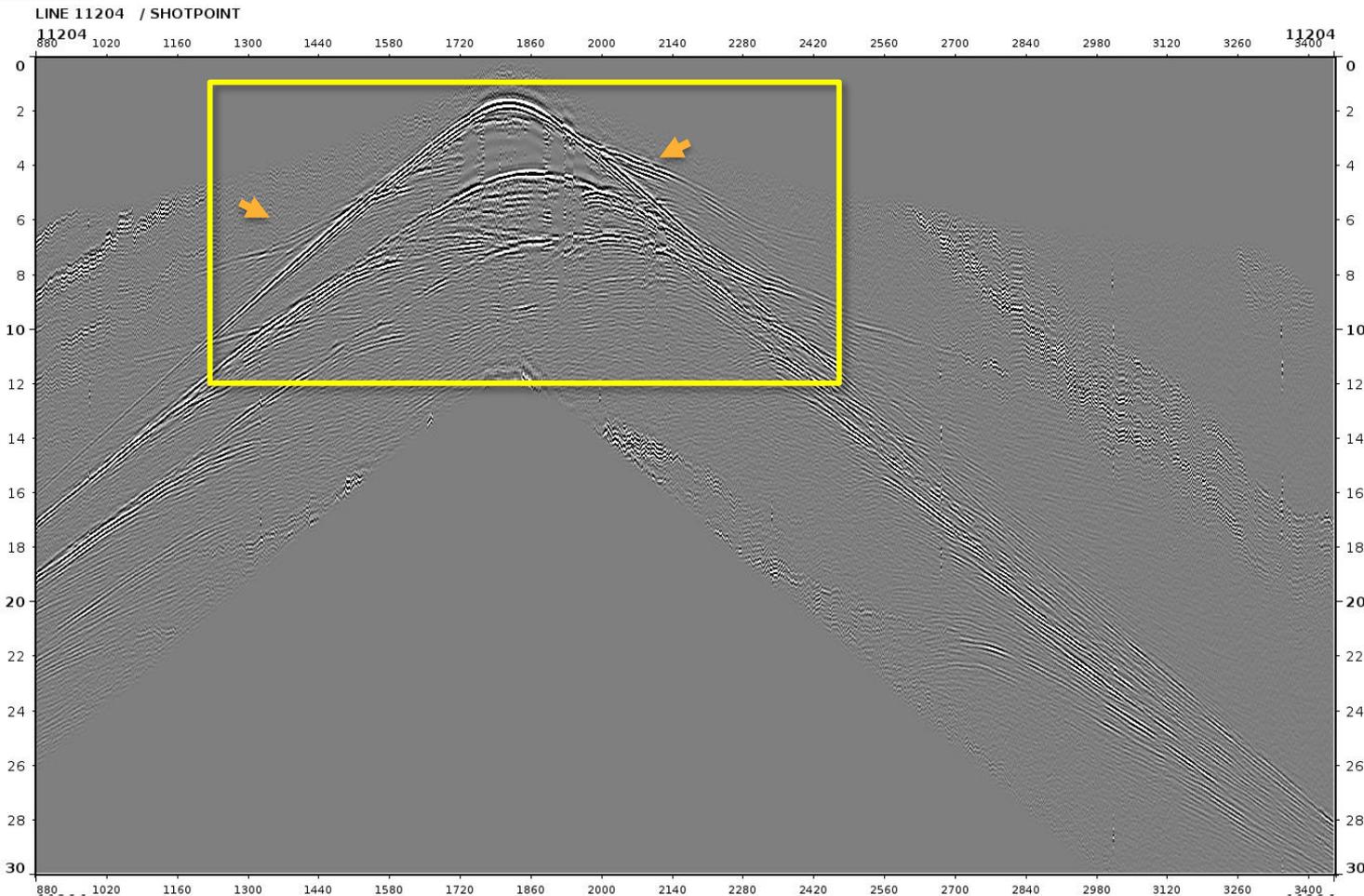
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- Mismatches at far offset remains, where ISO FWI may suffer from cycle skipping due to large velocity error in deep section.

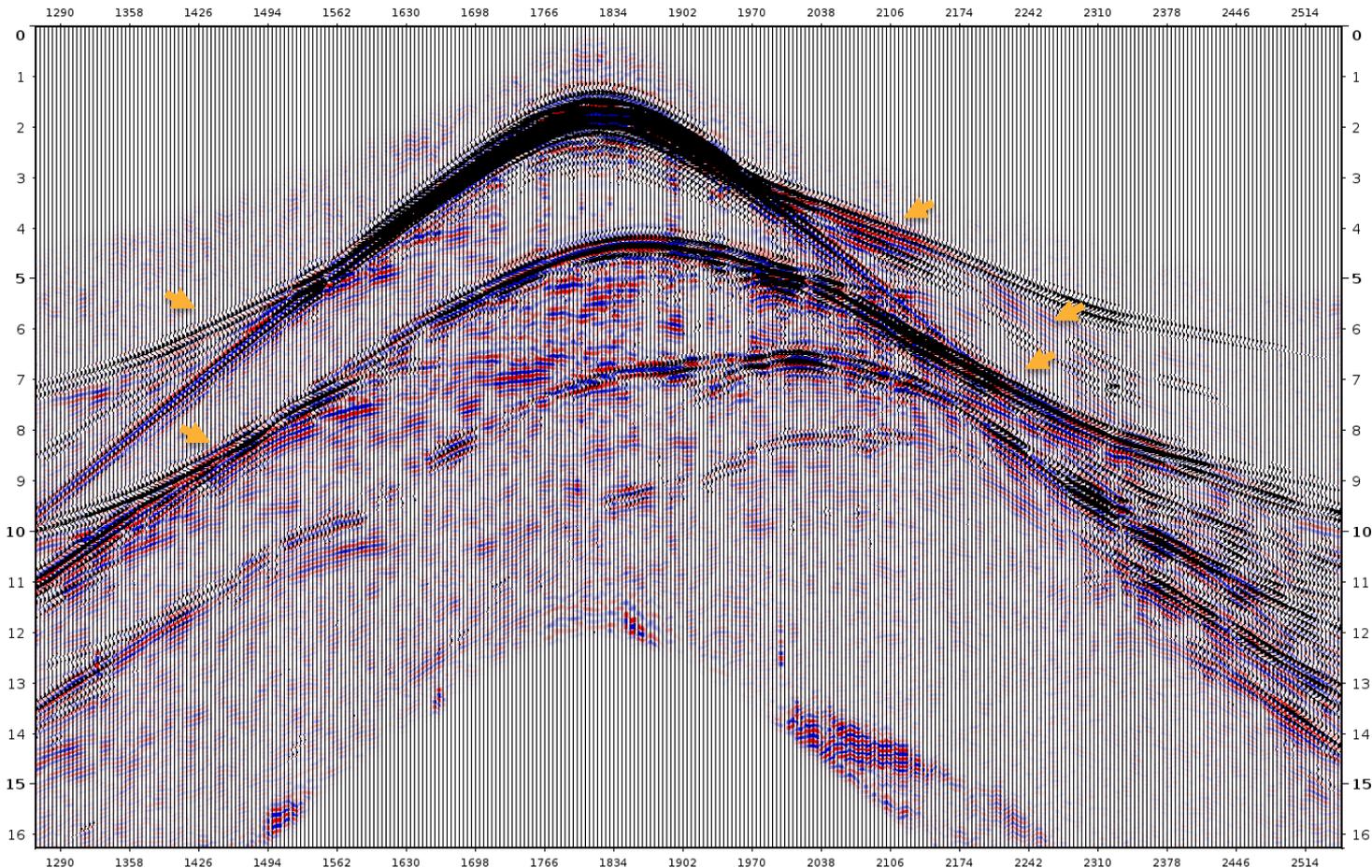


- After ISO FWI date, synthetic shots and real data matches better.
- Mismatches at far offset remains, where ISO FWI may suffer from cycle skipping due to large velocity error in deep section and/or anisotropic effect.

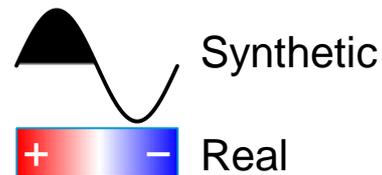


# OBS 058 Synthetic Overlaid on Real: Initial Velocity

LINE 11204 / SHOTPOINT

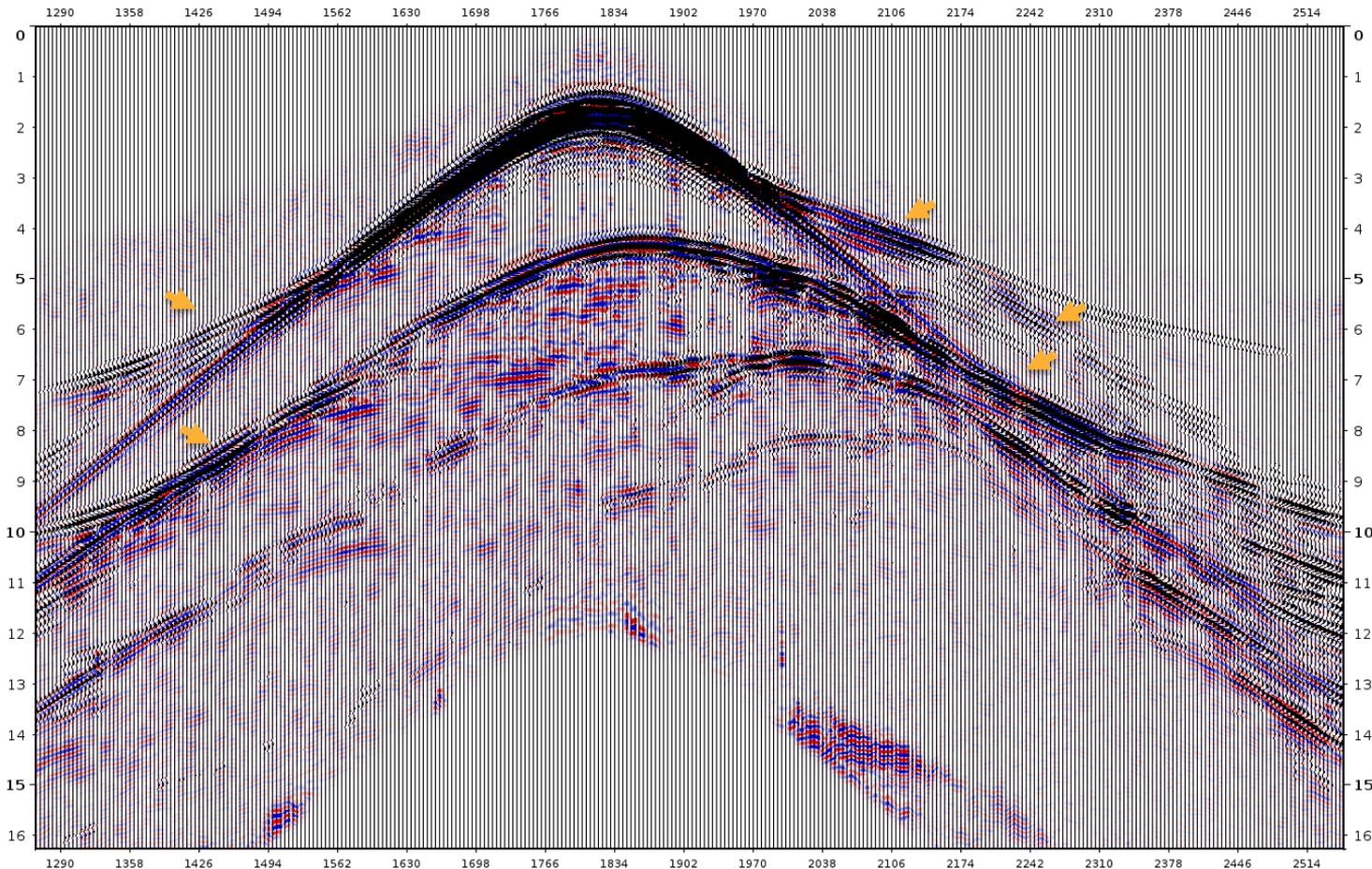


- With initial velocity, synthetic shot and real data matches not very well.

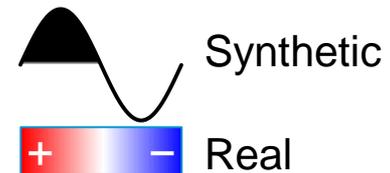


# Streamer 001 Synthetic Overlaid on Real: ISO FWI Velocity

LINE 11204 / SHOTPOINT



- After ISO FWI date, synthetic shots and real data matches better.
- Mismatches at far offset remains, where ISO FWI may suffer from cycle skipping due to large velocity error in deep section and/or anisotropic effect.



- ISO FWI gives reasonable update that follows geology down to ~2km beneath water bottom.
- Deeper than 2km beneath water bottom, we have less confidence due to increasing chances of cycle skipping and/or anisotropic effects.
- We plan to use reasonable update to continue with ISO tomography, which may provide better starting model for TTI FWI, especially in the deep section.