

[illegible]

R/V Marcus G Langseth
MGL_Single_Streamer

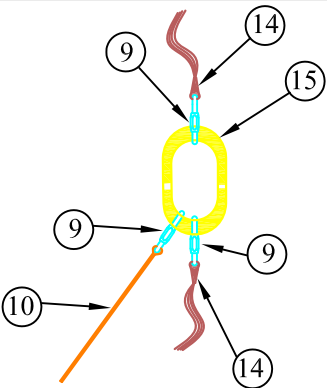
The diagram illustrates the cable system for the ROV 'FRODO'. The ROV is shown at the top left, with various internal components and external sensors. Four orange cables extend from the ROV, passing through a series of pulleys and a yellow sensor labeled 'FloT, FloTec PIV2000'. The cables then branch out to connect to a series of modules along a blue cable. These modules include a blue STU (Surface Tether Unit), a green AA01 (Acoustic Alibi), a red AB01 (Acoustic Beacon), a blue M39 (Mooring), a green AA02 (Acoustic Alibi), a red AB02 (Acoustic Beacon), a blue M38 (Mooring), a red AB03 (Acoustic Beacon), and a blue M37 (Mooring). The cable is labeled with 'CNG' (Cable Numb) and 'S40' (Surface Cable Number). The ROV is also labeled 'FRODO'.

Not used in this Configuration

1	RJS	DM	Updated to MGL 2D Configuration	2011-06-15
Version	Created by	Verified by	Changed/Updated	Date
LDEO Columbia University 61 Route 9W Palisades, New York 10964				

Inner-Leadin Connection

Not used in this Configuration



Not used in this Configuration