

LAMONT DATA REDUCTION CRUISE SUMMARY

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CRUISE: EW9301

START: 16 May 1993 [136] Jacksonville, Florida

20 May 1993 [140] Newark arrival

22 May 1993 [142] Newark departure

END: 23 May 1993 [143] Woods Hole, Mass.

PURPOSE: transit & shake down after shipyard period

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DATA REDUCTION: William J. Robinson

TIME:

Instrument: Kinematics GPS Synchronized clock, Model GPS-DC

Logging: 60 second intervals

Notes:

- (1) During the cruise EW9301 a program was developed to continuously adjust the CPU time of the logging computer to the UTC time from the GPS clock. This development involved some experimenting and debugging of the software and this work induced some errors in the CPU time tags for days 136 - 139. These errors were corrected by examining the GPS position times for both the Magnavox T-Set receivers and the Magnavox MX-4200D receivers. The corrections to the CPU time tags are listed in the table below.

day	time	required adjustment
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136	2300-2359	-10 seconds
137	0000-2359	-10 seconds
138	0000-0906	-10 seconds
138	0907-2359	seconds
139	0000-0250	seconds
139	0252-0257	seconds
139	0258-2359	0 seconds

No adjustment was needed for days 140-143.

- (2) The logged files of CPU time vs GPS clock time, the "tr1.d" files were discarded as they were erroneous and would just add confusion to this problem.

- (3) The data files for Furuno, Transit fix, GPS T-Set ("gp1.d" and "gp2.d"), GPS 4200 ("gp3.d" and "gp4.d"), PCO2, and sea temperature were corrected for the time errors.

(4) The Hydrosweep swath ("hs.d") and center beam ("hb.d") files were not corrected as their time tags are from another logging computer and there seems to be an additional problem reconciling the times on the Hydrosweep computer (SGI: "olive") and the general logging computer (SUN: "moray").

SPEED AND HEADING:

Instrument: Furuno CI-30 2-axis doppler speed log
Logging: 3 second intervals
Checking: visual check of plot of data
Smoothing: mean value of all good values within the same minute
Notes:
 (1) see notes under "TIME" above

TRANSIT SATELLITE FIXES:

Instrument: Magnavox MX-1107RS dual frequency Transit satellite receiver
Logging: all fixes from Transit #2 (bridge)
Notes:
 (1) see notes under "TIME" above

GPS SATELLITE FIXES:

Instrument: Magnavox MX-4200D Global Positioning System receiver
Logging: 10 second intervals
Checking:
 minimum number of sats: 3
 dilution of precision (DOPs) maximum: north = 4.0, east = 4.0
 compared GPS speed and course with Furuno smooth speed and heading
 compared positions with Transit-Furuno navigation
 reject fixes producing Eotvos correction errors in gravity
Smoothing: positions at 00 and 30 seconds of each minute were extracted
 from the logged data and then smoothed with a 41 point running average
Notes:
 (1) see notes under "TIME" above

- (2) The GPS data has a sinusoidal-like wave in it which is assumed to come from some degrading of the GPS quality for civilian users. This wave seems to vary in period and shape and is not a perfect sine curve. The periods are less than 20 minutes. The amplitudes and period will vary over 24 hours but always seem to be present in the data. This degrading produces a false ship's track for realtime navigation and introduces extreme errors, up to 6 mGals, in the Eotvos correction for the gravity. To handle this problem the following steps have been used to process the GPS:
1. the smoothing has been increased from a 9 point (4 minute) running average of the interpolated positions to a 41 point (20 minute) running average.
 2. this smooth GPS data is deleted at turns because the heavy smoothing greatly "widens" the turns.
 3. the remaining smooth GPS data is decimated to 20 minute intervals

These GPS processing steps, together with using the smooth speed and heading data from the Furuno for DR'ing between the decimated GPS positions produces good navigation and gravity data.

This degraded GPS quality has been observed since January 1992.

- (3) used MX-4200 "gp3" for all days except day 140 when "gp4" was used.

NAVIGATION:

A "1 minute navigation" is produced from the GPS and Furuno sources. The smooth speed and heading data is used to fill the gaps between the processed GPS positions by computing 1 minute DR'ed positions corrected for set and drift. The DR'ed positions are produced at 00 seconds of each minute.

BATHYMETRY:

Instrument: Atlas Hydrosweep DS

Logging: every ping

Notes:

- (1) see notes under "TIME" above; especially note (4)

GRAVITY:

Instrument: Bodenseewerks KSS-30 Marine Gravity meter

Logging: mGal values at 6 second intervals

Smoothing: mean values at 00 seconds of each minute calculated from the logged values +30 seconds of this time. This stage also adjusts the times of the smoothed values for a 75 second delay due to the filtering of the gravity by the KSS-30.

Merge with navigation: calculate Eotvos correction and Free Air Anomaly. The velocities, from the navigation, used in the Eotvos correction are smoothed with a 5 point running average for all days

Checking: visual check of plot of data to determine satisfactory Eotvos corrections, delete spikes of data at turns

Dc shift: -980167.40 mGal (from Jacksonville tie of 13 May 93)

Drift rate: 0.205 mGal per day (between Jacksonville and Newark)

Tie date: 13 May 1993 (day 133) at 1845 Z

Dc shift: -980165.76 mGal (from Newark tie of 21 May 93)

Drift rate: -0.018 mGal per day (between Newark and Woods Hole)

Tie date: 21 May 1993 (day 141) at 1744 Z

Lamont Database: Free Air Anomaly value at 00 seconds of each minute.
1930 theoretical gravity formula.

Notes:

- (1) see notes under "TIME" above

Instrument: Bodenseewerks KSS-30 Marine Gravity meter

Logging: BGM-3 counts at 1 second intervals

Notes:

- (1) see notes under "TIME" above
- (2) BGM-3 data was not processed
- (3) BGM-3 was removed in Newark