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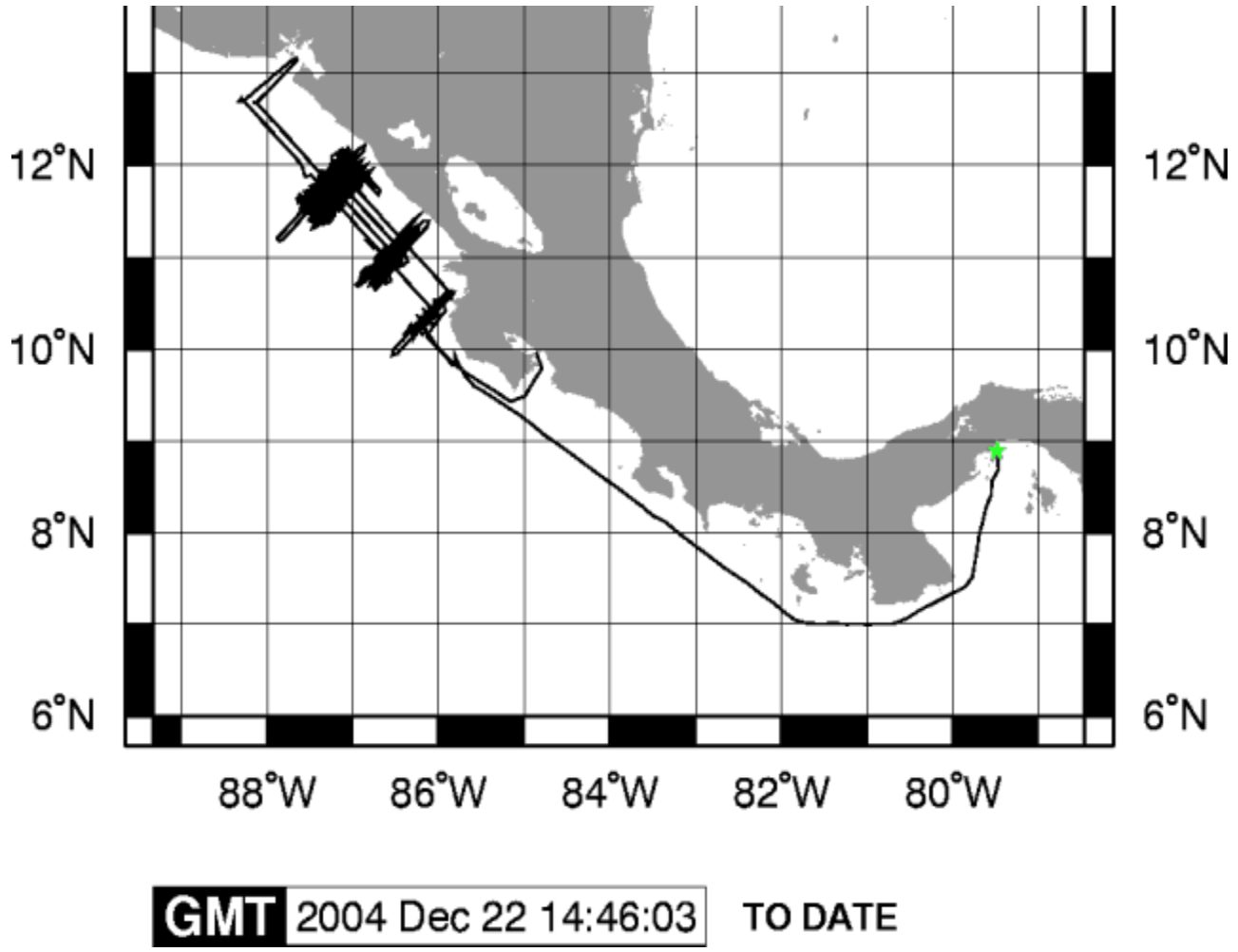
R/V Maurice Ewing Data Reduction Summary

EW–0412 Puntarenas, Costa Rica– Balboa, Panama

Date	Julian Date	Time	Port
November 22, 2004	326	14:05:00	Puntarenas, Costa Rica
December 22, 2004	357	22:13:30	Balboa, Panama



Project Summary

DESCRIPTION

Background and Scientific Objectives

High−Resolution, multichannel seismic (MCS) reflection data were collected from the inner shelf to the slope, in the Sandino forearc basin, offshore Costa Rica, Nicaragua, Honduras, and El Salvador by the University of Texas Institute for Geophysics (UTIG). The survey was designed to image Neogene depositional sequences indicative of sea−level change and stratal geometries that may reflect local tectonic history.

Cruise Members

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Cruise Notes

All data in this report is logged using GMT time and Julian days in order to avoid confusion with local time changes.

Hydrosweep

The hydrosweep performed normally

Gravity

The gravimeter performed normally.

Magnetics

The magnetometer performed normally. The magnetometer was pulled in during turns and through shallow water.

Raw data files from the megnetometer were incorrectly logged from the start of the cruise up through day 335. Raw data files from 328 to 331are missing signal strength values and the first digit of field strength. Raw data from days 331 to 335 are missing signal strength; field strength is OK. Raw data logging is good starting at about 335+21:25. All erroneous raw data logging was corrected for reduction purposes.

Navigation

Navigation operated normally.

Seismic

Seisnet was deemed too unreliable at the start of the cruise. 3490 tapes were carried to Heezen, the seismic tape station, and copied to disk and backup tapes as they were written.

Syntrak and the GCS90 operated normally.

Timing

Timing operated normally.

Data Logging

The R/V Maurice Ewing data logging system is run on a Sparc Ultra Enterprise Server. Attached are 48 serial ports via 3 16−port Digi International SCSI Terminal Servers. Generally, all data logged by the Ewing Data Acquisition System (DAS) is time stamped with the CPU time of the server, and broadcast to the Ewing network using UDP packet broadcasts. The CPU time of the server is synchronized to a UTC gps time clock.

GPS times are also time−tagged with cpu time, although the time of the GPS position is from the GPS fix itself.

The following tables describe the data instruments which performed logging during this cruise. The tables associated with the instruments describe logging periods and data losses for that instrument.

Time Reference

DATUM

logging interval: 30 min
file id: tr2

Used as the CPU synchronization clock. This clock is polled once every thirty minutes to synchronize the CPU clock of the data logger to UTC time. The logger (octopus) is responsible for updating the times of the other CPUs.

This clock was running and synchronizing the system the entire cruise.

Interruption s greater than 30 minutes are displayed in the following table

Log Date	LogDate	Comment
2004+326:14:05:00		Logging officially started
2004+357:13:30:00		Logging officially ends

GPS Receivers

GPS data is usually logged at 1−2 second intervals. The NMEA strings GPGGA and GPVTG are logged for position, speed, and heading fixes. This data was logged constantly throughout the cruise.

The POS/MV with the CNAV GcGPS as an auxiliary input was the primary gps for this cruise.

Trimble Tasmon P/Y Code Receiver

logging interval: 2 seconds
file id: gp1

The Tasmon is the primary GPS receiver for the Ewing Logging system and the primary GPS for Spectra fixes. The accuracy is around 15 meters. There were no interruptions during this

cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2004+326:14:05:00		Logging officially started
2004+357:13:30:00		Logging officially ends

Trimble NT200D

logging interval: 2 seconds
file id: gp2

The Trimble is the secondary receiver for GPS data. Data is logged at 2 second intervals and is also used as an input to Spectra, although it is weighed at a lower value than the Tasmon receiver.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2004+326:14:05:00		Logging officially started
2004+357:13:30:00		Logging Ends

C−Nav

logging interval: 2 seconds
file id: gp3

The C−Nav is a global satellite−based differential receiver. This is the best individual receiver currently on the ship.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2004+326:14:05:00		Logging officially started
2004+357:13:30:00		Logging Ends

POS/MV

logging interval: 1 second
file id: gp4

The POS/MV is a receiver which uses C−Nav input, its own antennae, an inertial sensor, and optional RTG, WTC, or WAAS corrections (when available) and a kalman filter to produce a smooth nav output and very accurate heading. As of June 2003 it is used as the primary GPS for Hydrosweep, as an input to Spectra, and can be used as the gps for reduction processing. With the C−Nav auxiliary input, this is the most accurate receiver on the ship.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2004+326:14:05:00		Logging officially started
2004+357:13:30:00		Logging Ends

Speed and Heading

Furuno CI−30 Dual Axis Speed Log
Sperry MK−27 Gyro

logging interval: 3 seconds
file id: fu

The Furuno and Gyro are combined to output speed, heading and course information to a raw Furuno file, as well as an NMEA VDVHW signal used as an input to various systems including steering and Spectra.

Interruptions greater than 30 minutes are displayed in the following table

Log Date	Log Date	Comment
2004+326:14:05:00		Official start date
2004+357:13:30:00		Official end date

Gravity

Bell Aerospace BGM−3 Marine Gravity Meter System

logging interval: 1 second
file id: vc. (raw), vt. (processed)
drift per day: 0.018

The BGM consists of a forced feedback accelerometer mounted on a gyro stabilized platform. The gravity meter outputs raw counts approximately once per second which are logged and processed to provide real−time gravity displays during the course of the cruise as well as adjusted gravity data at the end of the cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	Log Date	Comment
2004+326:14:05:00		Official start date
2004+357:13:30:00		Official end time

Bathymetry

Krupp Atlas Hydrosweep−DS2

logging interval: variable based on water depth
file id: hb (centerbeam), hs (swath)

The hydrosweep full swath data is continuously logged for every cruise, and centerbeam data is extracted and processed separately. The centerbeam operates at a logging frequency dependent on the water depth.

The full swath data is not routinely processed, but can be processed with the MB−System software which can be downloaded for free. For instructions, use the website:

http://www.ldeo.columbia.edu/MB−System.

MBSystem, version 5.0beta3 is necessary to process data after June 1, 2001.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2004+326:14:05:00		Official start logging
2004+357:13:30:00		Official end logging

Weather Station

RM Young Precision Meteorological Instruments, 26700 series

logging interval: 1 minute
file id: wx

The weather station is used to log wind speed, direction, air temperature, and barometric pressure. We log this information at 1−minute intervals.

Log Date	LogDate	Comment
2004+326:14:05:00		Official start logging
2004+357:13:30:00		Official end logging

Magnetics

Geometrix G−882 Magnetometer

logging interval: 10 seconds
file id: mg

The magnetometer employs a Cesium atomic magnetic resonance system operating as the frequency controlling element of an oscillator. The frequency of the oscillation varies directly with the external magnetic field at the sensor.

The magnetometer was frequently pulled in during turns and through shallow water.

The following table shows the times the magnetometer was logging

Start Log Date	End LogDate	Comment
2004+326:14:05:00		Offical start logging
2004+357:13:30:00		Official end logging

There are several files for each line reflecting the line status:

File	Description
ts.n	Shot time is merged with Ewing navigation to determine shot location
nb2.r	Navigation is from Spectra, and includes tailbuoy, tailbuoy range and bearing

Location1

EW0410 San Diego, CA

Pier/Ship	Latitude	Longitude
	8 57.105 N	79 34.

Scripps Pier on Rosecrans Street

Reference	Latitude	Longitude
	32 42.399N	117 14.187

EW0406 gravity tie reference.

	Id	Julian	Date	Mistie	Drift/Day	Prev Mistie
Pre Cruise	EW0409	288	14. Oct 04	11.01	0.35	−5.53
Post Cruise	EW0410	309	04. Nov 04	−3.51	−0.692	11.01
Total Days			21.00	−14.52		

Time	Entry	Value	
0	CDeck Level BELOW Pier	0.00	
15:50:00	Pier 1 L&R Value	1910.10	L&R
15:55:00	Reference L&R Value	1910.15	L&R
16:05:00	Pier 2 L&R Value	1910.11	L&R
	Reference Gravity	978222.54	mGals
	Gravity Meter Value (BGM Reading)	978233.20	mGals
	Potsdam Corrected	1	1 if corrected

*Gravity meter is **5.5** meters below CDeck*

Difference in meters between Gravity Meter and Pier: 2.00 meters

Height Cor = Pier Height*	FAA Constant				
2.00	0.31			0.62	mGals/min

Difference in mGals between Pier and Gravity Meter

Pier (avg) −	Reference *	1.06 L&R/mGal		Delta L&R	
1910.11	1910.15	1.06		−0.05	mGals

Gravity in mGals at Pierside

Reference + Delta mGals [+ Potsdam]				Pier Gravity	
978222.54	−0.05	13.60		978236.09	mgals

Gravity in mGals at Meter

Pier Gravity+	Height Correction			Gravity@meter	
978236.09	0.62			978236.71	mGals

Current Mistie

BGM Reading−	Calculated Gravity			Current Mistie	
978233.20	978236.71			−3.51	mGals

EW0412 Balboa, Panama

Pier/Ship	Latitude	Longitude
	18 27.84N	66 06.36W
Pier 2		
Reference	**Latitude**	**Longitude**
	18 27.8N	66 05.5W
Cruise Ship terminal		

	Id	Julian	Date	Mistie	Drift/Day	Prev Mistie
Pre Cruise	EW0410	326	04. Nov 04	−5.53	0.15	8.99
Post Cruise	EW0412	357	22. Dec 04	**−2.59**	**0.061**	**−5.53**
Total Days			**48.00**	**2.94**		

Time	Entry	Value	
1446	**CDeck Level BELOW Pier**	2.00	
1446	**Pier 1 L&R Value**	2332.11	**L&R**
1446	**Reference L&R Value**	2334.21	**L&R**
	Pier 2 L&R Value	2332.11	**L&R**
	Reference Gravity	978680.69	**mGals**
	Gravity Meter Value (BGM Reading)	978691.80	**mGals**
	Potsdam Corrected	1	**1 if corrected**

*Gravity meter is **5.5** meters below CDeck*

Difference in meters between Gravity Meter and Pier: **7.50** meters

Height Cor =	Pier Height*	FAA Constant			
	7.50	**0.31**			**2.33** mGals/min

Difference in mGals between Pier and Gravity Meter

Pier (avg) −	Reference *	1.06 L&R/mGal		Delta L&R
2332.11	**2334.21**	**1.06**		**−2.23** mGals

Gravity in mGals at Pierside

Reference + Delta mGals [+ Potsdam]				Pier Gravity
978680.69	**−2.23**	**13.60**		**978692.06** mgals

Gravity in mGals at Meter

Pier Gravity+	Height Correction			Gravity@meter
978692.06	**2.33**			**978694.39** mGals

Current Mistie

BGM Reading−	Calculated Gravity			Current Mistie
978691.80	**978694.39**			**−2.59** mGals

For all formats, a – in the time field means an invalid value for some reason.

Streamer Compass/Bird Data cb.r

This data is not processed, but can still be found in the "processed" data directory.

```
Shot Time               Line     Shot     Latitude      Longitude

2000+079:00:08:40.085  strike1 000296  N 15 49.6217 W 060 19.8019

2nd GPS Position                      Tailbuoy Position
Latitude     Longitude                Latitude     Longitude

N 15 49.6189 W 060 19.8101    N 15 47.1234 W 060 20.1901

Furuno  Streamer
Gyro    Compasses & Heading

344.1       C01 2.3 C02 1.7  ...
```

Gun Depths dg

Gun depths in tenths of meters. There will always be 20 gundepths even if only one gun was configured and shooting.

```
                        Gun Depths
Shot Time               1   2   3  4    5   6   7   8   9  ...  20

2001+089:06:47:05.909 189 068 005 005 096 005 060 054 005 ... 6
```

Raw Furuno Log fu.s

This data has been smoothed and output 1 fix per minute.

```
CPU Time Stamp         Track Speed Hdg   Gyro

2000+166:00:01:53.091 –     4.4   140.5 148.3
```

Hydrosweep Centerbeam hb.n

Hydrosweep data merged with navigation

```
                              Centerbeam
CPU Time Stamp       Latitude Longitude          Depth

2000+074:09:55:00.000  N 13 6.6206    W 59 39.3908   134.9
```

Merged Data m

```
                                                        GPS
CPU Time Stamp         Latitude     Longitude          Used  Set  Drift Depth

2000+200:12:25:00.000  N 45 54.1583 W 42 47.1770       gp1   0.0  0.0

Magnetic                        Gravity
Total Intensity   Anomaly     FAA  GRV       EOTVOS   Drift   Shift

49464.7           55.5        22.2 980735.0   –8.4     –0.1     2.8

Temperature Salinity Conductivity

0.0         0.0      0.0
```

The gravity drift and shift are values that have been added to the raw gravity to make up for drift in the meter that has been lost in accordance with a gravity check at each port stop.

Temperature,Salinity and Conductivity will only be valid while logging a Thermosalinograph, which is not usually the case.

Magnetics Data — mg.n

- A minus sign in the time stamp is flagged as a spike point, probably noise...
- Anomaly is based on the International Geomagnetic Reference Field revision 2000

```
CPU Time Stamp        Latitude     Longitude      Raw Value Anomaly
200+077:00:23:00.000 N 16 11.2918 W  59 47.8258 36752.2   -166.8
```

Navigation File — n

```
CPU Time Stamp         Latitude     Longitude       Used  Set  Drift
2000+074:00:03:00.000 N 13 6.2214  W  59 37.9399   gp1   0.0   0.0
```

Navigation Block — nb0

Navigation is a compendium of Ewing logged data at shot time. The shot position here is the shot position from the Spectra system.

```
Shot Time               Shot # CPU Time               Shot Position
2001+088:00:00:00.606 016967 2001+088:00:00:03.031 N 30 11.8324 W 042 10.8162

Water  Sea    Wind   -------------Tailbuoy----------------- Line
Depth  Temp Spd  Dir Latitude     Longitude     Range Bearg Name   Speed Heading
2565.1 20.7 16.4 164 N 30 12.0427 W 042 14.7319 6296.3 93.5 MEG-10 4.2   101.1
```

Tailbuoy Navigation — tb1.c

Raw tailbuoy fixes

```
CPU Time Stamp         Latitude     Longitude       GPS Precision
2001+088:00:00:02.000 N 30 12.0424 W 042 14.7309   SA
```

GPS Precision is either SA, DIFF or PCODE

Ewing Processed Shot Times — ts.n

Shot times and positions based on the Ewing navigation data processing

```
CPU Time Stamp         Shot # Latitude     Longitude     Line Name Centerbeam Depth
2000+079:00:08:01.507 000295 N 15 49.5703 W 060 19.7843 strike1     2345.6
```

Shot Data Status — ts.n.status

The ts.nxxx.status file describes the line information for that day, giving some basic statistics about the line: start, end times; missing shots; start and end shots.

```
LINE   strike1: 98+079:00:00:15.568 : 000283 .. 002286
        MISSING: 347, 410, 1727
LINE   dip2: 98+079:23:05:22.899 : 000002 .. 000151
```

This example says that on Julian Day 079 of 1998, two lines (strike1 and dip2) were run: the end of strike 1 (shots 000283 to 002286) and the start of dip2 (shots 000002 to 000151).

Line strike1 had some missing shots in the data file (probably missing on the SEG-d header as well).

Spectra Shot Times — nb2.r

The shot times and positions based on the Spectra positioning; with raw tailbuoy range and bearing.

```
CPU Time Stamp          Shot # Latitude      Longitude      Line Name
2001+084:00:00:05.924 009245 N 23 31.2410 W 045 25.0894

                                 Tailbuoy
Latitude      Longitude      Range  Bearing  Line Name
N 23 30.4540 W 045 21.4338 6389.8 283.2    KANE-4
```

Raw Gravity Counts — vc.r

sample BGM-3 gravity count record (without time tag):

```
pp:dddddd ss
|    |    |___________ status: 00 = No DNV error; 01 = Platform DNV
|    |                         02 = Sensor DNV;   03 = Both DNV's
|    |________________ count typically 025000 or 250000
|_____________________ counting interval, 01 or 10
                       The input of data can be at 1 or 10 seconds.
```

Gravity Data — vt.n

* A minus sign in the time stamp is flagged as a spike point
* m_grv3 calculates the Eotvos correction as:
  eotvos_corr = 7.5038 * vel_east * cos(lat) + .004154 * vel*vel
* The theoretical gravity value is based upon different models for the earth's shape.
  - 1930 = 1930 International Gravity Formula
  - 1967 = 1967 Geodetic Reference System Formula
  - 1980 = 1980 Gravity Formula
* The FAA is computed as:
  faa = corrected_grv – theoretical_grv
* Velocity smoothing is performed w/ a 5 point window

```
CPU Time Stamp          Latitude      Longitude      Model FAA      RAW
2000+148:00:10:00.000 N 09 34.7255 W 085 38.5826 1980  9.48    978264.16

Eotvos  Drift DC      Raw  Velocity     Smooth Velocity
Smooth  Total Shift   North     East     North    East
-74.78  0.06  4.16    1.875 -10.373     1.927 \10.166
```

Datum Time — ts2.r

```
CPU Time                Datum Time        Time Reference
2001+069:00:15:29.727 069 00 15 29.378 datum
```

Raw GPS — gp(12).d, tb1.d

Raw GPS is in NMEA Format.

Meteorological Data wx

```
                          True
CPU Time Stamp          Spd Dir

2001+045:00:00:00.967   7.8  22

Bird1:                                                Bird 2
Speed                      Direction                  Speed                      Direction
Inst  60sA   60mA  60sM  Inst 60sA 60mA              Inst  60sA  60mA  60sM    Inst 60sA 60mA

7.8   6.6    8.5   16.8  277  291  5                 0.0   0.0   0.0   0.0     0    0    0

Temperature                    Humidity
Inst  60mA  60mm  60mM         Inst 60mm 60mM          Barometer

15.0  14.2  14.3  15.1         92   90   93            1027.5

Inst:       Current
60sA:       60 second average
60mA:       60 minute average
60sM:       60 second maximum
60mm:       60 minute minimum
60mM:       60 minute maximum
```

Merged Meteorological Data mmet

```
TSG, WX, CT merged with Nav at 1 minute fixes
date        time        lat       lon       gpu head spd
2001+244:00:00:00.000 12.14071 44.98469 gp1 10.2 83.0

tws  twd   temp hum  press  cti  cte  con sal  ct
26.5 228.0 30.6 87.0 1000.8 28.8 28.8 5.9 36.3 28.8

gpu  = gps unit in use
head = ship's heading
spd  = ship's speed in knots
tws  = true wind speed
twd  = true wind direction
temp = air temp (celcius)
hum  = relative humidity (%)
press= pressure in mb
cti  = sea temp from the internal TSG sensor
cte  = sea temp from the external TSG sensor
con  = conductivity, Siemens/meter
sal  = salinity, practical salinity units
ct   = sea temp from the C-keel sensor (to tenths of a degree)
```

Shot Times from Spectra P1 Files shots.p1

```
These files were created with the script: extract_shots_from_p1 -a 1
Epoch Time    Shot#  Source Lat/Lon         TB Lat      TB Lon
985788741.000 015570 30.283881 -41.854536  30.320144  -41.886642
Vessel Ref Lat/Lon   Antenna GPS Lat/Lon     Water Depth
```

30.283478 −41.854117 30.283531 −41.854078 2894.2

- Source is the Center of the Guns
- TB is the Tailbuoy, according to Spectra
- Vessel Ref is the location of the center of the Mast
- Antenna GPS is the location of Antenna 1 (−a 1 flag); in this case is the Tasmon GPS
- Water Depth is the HS Centerbeam depth

Shot Times from Spectra P2 Files — shots.p2

These files were created with the script: *extract_shots_from_p2 −o "V1 G1"*

Epoch Time Shot# Vessel Ref Lat/Lon Source Lat/Lon

985716772.4 00015572 30.282803 −41.866136 30.283207 \41.866540

- Vessel Ref is the location of the center of the Mast
- Source is the Center of the Guns

Tape Contents

EW0412

Cruise_Report_EW0412.pdf	this document
ew0412.cdf	NetCDF database file of this cruise
ew0410.cdf.nav	NetCDF database file of this cruise' navigation
configs/	Ewing Data System configuration files
docs/	File Formats, Spectra manuals
processed/	Processed datafiles merged with navigation
trackplots/	daily cruise track plots (*postscript*)
mbsystem/	Latest MBSystem source code
raw/	Raw data directly from logger
reduction/	Reduced data files
clean/	daily processing directory, includes daily postscript plots of the data.