

Lamont– Doherty Earth Observatory
Office of Marine Affairs
61 Route 9W
Pallsades, NY 10969

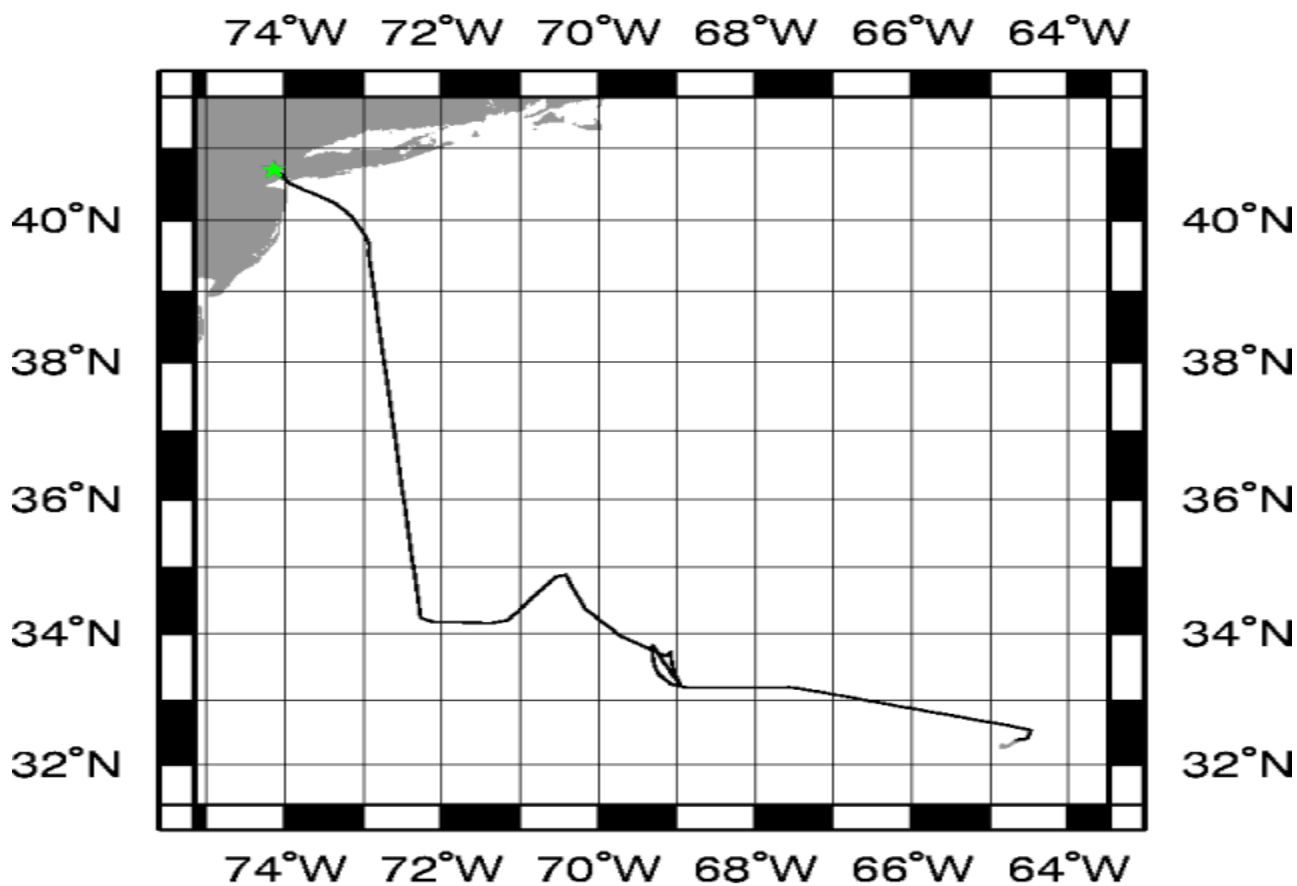
Prepared By: Ethan Gold
etgold@ldeo.columbia.edu
845 365-8677



R/V Maurice Ewing Data Reduction Summary

EW0310 St. George, Bermuda – Newark, NJ

Date	Julian Date	Time	Port
November 14, 2003	318	12:00 UTC	St. George, Bermuda
November 20, 2003	324	12:00 UTC	Newark, NJ



GMT 2003 Nov 20 19:31:37 **TO DATE**

Project Summary

DESCRIPTION

Background and Scientific Objectives

Investigation of the structure beneath the Bermuda Rise.

The cruise was cancelled after four days out before any work could be done due to permitting problems at the last minute.

Cruise Members

Science Party

Marcia McNutt	Chief Scientist	mcnutt@mbari.org
David Caress	scientist	caress@mbari.org
Kelsey Jordahl	scientist	kels@mbari.org
Jackie Floyd	scientist	jsfloyd@ldeo.columbia.edu
Bethany March	scientist	bethemarch@hotmail.com
Tony Ramirez	scientist	tony@mbari.org
Peter Richardson	scientist	p_richardson@coloradocollege.edu
Crispin Hollinshead	scientist	chollins@igpp.ucsd.edu
David Willoughby	scientist	dfwilloughby@cox.net
Mark Gibaud	scientist	mgibaud@ucsd.edu
Bruce Mactavish	Chief MMO	bmactavish@lgl.com
Howie Goldstein	MMO	hgold@ewing.ldeo.columbia.edu
Sarah Stoltz	MMO	stoltz@ewing.ldeo.columbia.edu

Ship's Science

Robert Haedge	Syntron Technician	haedge@ewing.ldeo.columbia.edu
Ropate Maiwiriwiri	Core Bosun	ropate@ldeo.columbia.edu
Ethan Gold	Sysadmin	etgold@ldeo.columbia.edu
John Collins	Science Officer	collins@ewing.ldeo.columbia.edu
Bill Robinson	ET	robinson@ewing.ldeo.columbia.edu
Shin Ae Tassia	Technician	shinae@ldeo.columbia.edu
John DiBernardo	Gunner	honey@ewing.ldeo.columbia.edu
John Byrne	Gunner	johnby@ewing.ldeo.columbia.edu
Justin Walsh	Gunner	cabinboy@ldeo.columbia.edu

Ship Crew

James O'Laughlin	Captain	captain@ewing.ldeo.columbia.edu
Al Karlyn	Chief Engineer	engine@ewing.ldeo.columbia.edu
Stanley Zeigler	1 st Mate	stan@ewing.ldeo.columbia.edu
Meredith Meketsy	2 nd Mate	mecketsy@ewing.ldeo.columbia.edu
Melannie Lovercheck	3 rd Mate	melannie@ewing.ldeo.columbia.edu
Miguel Flores	1 st A/Engineer	miguel@ewing.ldeo.columbia.edu
Matthew Ingerson	3 rd A/Engineer	ingerson@ewing.ldeo.columbia.edu
Mike Unger	3 rd A/Engineer	unger@ewing.ldeo.columbia.edu
Adrian Reed	Steward	adrian@ewing.ldeo.columbia.edu
Jeremy Beckett	A/B	jeremyb@ewing.ldeo.columbia.edu
Rebecca Hancock	A/B	rebecca@ewing.ldeo.columbia.edu

Kevin Fisher	Oiler	kevinf@ewing.ideo.columbia.edu
Moqo, Luke	Utility	luke@ewing.ideo.columbia.edu
Jim Syferd	O/S	jims@ewing.ideo.columbia.edu
Strickland, Leslie	Oiler	gordo@ewing.ideo.columbia.edu
Osorio, Nolan	O/S	nolan@ewing.ideo.columbia.edu
Wayne Reis	Cook	wayner@ewing.ideo.columbia.edu
Knight, Robert	Oiler	knight@ewing.ideo.columbia.edu
Greg Dalton	O/S	dalton@ewing.ideo.columbia.edu
Walker, Wakefield	Bosun	walker@ewing.ideo.columbia.edu

Cruise Notes

All data in this report is logged using GMT time and Julian days in order to avoid confusion with local time changes.

Hydrosweep

Hydrosweep operated normally. An experiment was performed to determine if variations in the POS/MV heave settings would alter an apparent heave error in the data. No significant change was detected in all three phases of the experiment.

Gravity

The Gravimeter was malfunctioning for the duration of the cruise. A gravity tie was not taken in Bermuda, though a nearby tie from 2.5 years previous suggested a reasonable at-rest value for the gravimeter in port, though dynamic operation produces junk data.

Magnetics

No data taken

Navigation

Navigation operated normally.

Time

No notes

Spectra

Spectra was configured, but never used except for testing. The new Syntrack software seems to play nicely with spectra, log_spectra, etc.

Data Logging

The R/V Maurice Ewing data logging system is run on a Sparc Ultra Enterprise Server. Attached are 48 serial ports via 3 16-port Digi International SCSI Terminal Servers. Generally, all data logged by the Ewing Data Acquisition System (DAS) is time stamped with the CPU time of the server, and broadcast to the Ewing network using UDP packet broadcasts. The CPU time of the server is synchronized once every half hour to a Datum UTC gps time clock.

GPS times are also time-tagged with cpu time, although the time of the GPS position is from the GPS fix itself.

The following tables describe the data instruments which performed logging during this cruise. The tables associated with the instruments describe logging periods and data losses for that instrument.

Time Reference

Datum StarTime 9390-1000

logging interval: 30 minutes
file id: tr2

Used as the visual UTC reference on top of the computer racks.

This clock was running and synchronizing the system the entire cruise.

Interruptions greater than 30 minutes are displayed in the following table

Log Date	LogDate	Comment
		Logging officially started
		Logging officially ends

JOETIME

logging interval: 30 minutes
file id: tr3

Used as the CPU synchronization clock. This clock is polled once every half hour to synchronize the CPU clock of the data logger to UTC time. The logger (octopus) is responsible for updating the times of the other CPUs.

This clock was running and synchronizing the system the entire cruise.

Interruptions greater than 30 minutes are displayed in the following table

Log Date	LogDate	Comment
2003+324:18:53:30.021		Logging officially started
2003+324:18:53:30.021		Logging officially ends

GPS Receivers

GPS data is usually logged at 1 – 2 second intervals. The NMEA strings GPGGA and GPVTG are logged for position, speed, and heading fixes. This data was logged constantly throughout the cruise.

Trimble NT300D

logging interval: 2 seconds
file id: gp2

The Trimble is the secondary receiver for GPS data. Data is logged at 2 second intervals and is also used as an input to Spectra, although it is weighed at a lower value than the Tasmon receiver.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2003+318:06:30:39.368		Logging officially started
2003+318:07:46:19.330	2003+318:14:25:29.292	Data Interruption
2003+319:00:03:06.463	2003+319:01:58:25.306	
2003+319:10:33:25.045	2003+319:12:34:06.223	
2003+319:13:14:57.032	2003+319:14:09:56.276	
2003+324:05:46:45.492	2003+324:14:15:25.346	
2003+324:16:46:21.068	2003+324:17:37:42.335	
2003+324:18:53:19.363		Logging Ends

C-Nav

logging interval: 2 seconds
file id: gp3

The C-Nav is a global satellite-based differential receiver. This is the best individual receiver currently on the ship.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2003+318:06:30:46.630		Logging officially started
2003+324:18:53:18.643		Logging Ends

POS/MV

logging interval: 1 second

file id: gp4

The POS/MV is a receiver which uses C-Nav input, its own antennae, an inertial sensor, and optional RTCM corrections (when available) and a kalman filter to produce a smooth nav output and very accurate heading. As of June 2003 it is used as the primary GPS for Hydrosweep, as an input to Spectra, and can be used as the gps for reduction processing. With the C-Nav auxiliary input, this is the most accurate receiver on the ship.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2003+318:06:30:56.657		Logging officially started
2003+324:18:53:20.272		Logging Ends

Speed and Heading

Furuno CI-30 Dual Axis Speed Log

Sperry MK-27 Gyro

logging interval: 6 seconds

file id: fu

The Furuno and Gyro are combined to output speed, heading and course information to a raw Furuno file, as well as an NMEA VDVHW signal used as an input to various systems including steering and Spectra.

Interruptions greater than 30 minutes are displayed in the following table

Log Date	Log Date	Comment
2003+318:06:31:15.027		Official start date
2003+324:18:53:20.610		Official end date

Gravity

Bell Aerospace BGM-3 Marine Gravity Meter System

logging interval: 1 second
file id: vc. (raw), vt. (processed)
drift per day: -0.205

The BGM consists of a forced feedback accelerometer mounted on a gyro stabilized platform. The gravity meter outputs raw counts approximately once per second which are logged and processed to provide real-time gravity displays during the course of the cruise as well as adjusted gravity data at the end of the cruise.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	Log Date	Comment
2003+318:06:30:33.599		Official start date
2003+324:18:53:19.872		Official end time

Bathymetry

Krupp Atlas Hydrosweep-DS2

logging interval: variable based on water depth
file id: hb (centerbeam), hs (swath)

The hydrosweep full swath data is continuously logged for every cruise, and centerbeam data is extracted and processed separately. The centerbeam operates at a logging frequency dependent on the water depth.

The full swath data is not routinely processed, but can be processed with the MB-System software which can be downloaded for free. For instructions, use the website:
<http://www.ideo.columbia.edu/MB-System>.

MBSYSTEM, version 5.0beta3 is necessary to process data after June 1, 2001.

Interruptions greater than 10 minutes are displayed in the following table

Log Date	LogDate	Comment
2003+318:06:32:44.000		Official start logging
2003+318:06:43:04.000	2003+318:15:21:50.000	
2003+320:01:02:07.000	2003+320:01:48:29.000	
2003+320:05:25:07.000	2003+320:05:36:51.000	
2003+321:03:31:00	2003+321:04:43:00	POS Heave to z-alt setting
2003+321:04:43:00	2003+321:05:38:00	POS Heave to 200 sec bdw
2003+321:05:38:00		POS Heave to orig 20 sec bdw
2003+324:05:12:35.000		Official end logging

Weather Station

RM Young Precision Meteorological Instruments, 26700 series

logging interval: 1 minute

file id: wx

The weather station is used to log wind speed, direction, air temperature, and barometric pressure. We log this information at 1-minute intervals.

Log Date	LogDate	Comment
2003+318:06:31:43.391		Official start logging
2003+324:18:53:00.259		Official end logging

Gravity Ties

LOCATION 1

EW0308 Bridgeport, Barbados

Pier/Ship	Latitude	Longitude
	13 06.07347N	59 37.75187W
Bridgeport Harbor		
Reference	Latitude	Longitude
No Lat/Lon available, (see map in gravity log).		

	Id	Julian	Date	Mistie	Drift/Day	Prev Mistie
Pre Cruise	EW0307	275	02. Oct 03	32.21	0.92	32.21
Post Cruise	EW0308	292	19. Oct 03	28.73	-0.205	0.00
Total Days			17.00	-3.48		

Time	Entry	Value	
16:10:00	CDeck Level BELOW Pier	0.30	
16:10:00	Pier 1 L&R Value	1966.10	L&R
15:50:00	Reference L&R Value	1967.58	L&R
16:30:00	Pier 2 L&R Value	1966.10	L&R
	Reference Gravity	978294.44	mGals
	Gravity Meter Value (BGM Reading)	978309.80	mGals
	Needs Potsdam Correction	1	1 if Potsdam referenced

Gravity meter is 5.5 meters below CDeck

Difference in meters between Gravity Meter and Pier	5.80	meters
Height Cor = Pier Height* FAA Constant	5.80	0.31
		1.80 mGals/min

Difference in mGals between Pier and Gravity Meter

Pier (avg) -	Reference *1.06 L&R/mGal	Delta L&R	
1966.10	1967.58	1.06	-1.57 mGals

Gravity in mGals at Pierside

Reference + Delta mGals [+ Potsdam]	IGSN-71 Referenced Pier	
978294.44	-1.57	-13.60
		978279.27 mgals

Gravity in mGals at Meter

Pier Gravity+ Height Correction	Gravity@meter	
978279.27	1.80	978281.07 mGals

Current Mistie

BGM Reading	Calculated Gravity	Current Mistie	
978309.80	978281.07		28.73 mGals

Gravity Ties

Location 2

File Formats

For all formats, a – in the time field means an invalid value for some reason.

Streamer Compass/Bird Data

cb.r

This data is not processed, but can still be found in the "processed" data directory.

<u>Shot Time</u>	<u>Line</u>	<u>Shot</u>	<u>Latitude</u>	<u>Longitude</u>
2000+079:00:08:40.085	strike1	000296	N 15 49.6217	W 060 19.8019
<u>2nd GPS Position</u>		<u>Tailbuoy Position</u>		
<u>Latitude</u>	<u>Longitude</u>	<u>Latitude</u>	<u>Longitude</u>	
N 15 49.6189	W 060 19.8101	N 15 47.1234	W 060 20.1901	
<u>Furuno Streamer Gyro Compasses & Heading</u>				
344.1	C01 2.3	C02 1.7	...	

Gun Depths

dg

Gun depths in tenths of meters. There will always be 20 gundepths even if only one gun was configured and shooting.

<u>Shot Time</u>	<u>Gun Depths</u>																		
	1	2	3	4	5	6	7	8	9	...	20								
2001+089:06:47:05.909	189	068	005	005	096	005	060	054	005	...	6								

Raw Furuno Log

fu.s

This data has been smoothed and output 1 fix per minute.

<u>CPU Time Stamp</u>	<u>Track</u>	<u>Speed</u>	<u>Hdg</u>	<u>Gyro</u>
2000+166:00:01:53.091	-	4.4	140.5	148.3

Hydrosweep Centerbeam

hb.n

Hydrosweep data merged with navigation

<u>CPU Time Stamp</u>	<u>Centerbeam</u>		<u>Depth</u>
	<u>Latitude</u>	<u>Longitude</u>	
2000+074:09:55:00.000	N 13 6.6206	W 59 39.3908	134.9

Merged Data

m

<u>CPU Time Stamp</u>	<u>Latitude</u>	<u>Longitude</u>	<u>GPS Used</u>	<u>Set</u>	<u>Drift</u>	<u>Depth</u>
2000+200:12:25:00.000	N 45 54.1583	W 42 47.1770	gp1	0.0	0.0	
<u>Magnetic</u>		<u>Gravity</u>				
<u>Total Intensity</u>	<u>Anomaly</u>	<u>FAA</u>	<u>GRV</u>	<u>EOTVOS</u>	<u>Drift</u>	<u>Shift</u>
49464.7	55.5	22.2	980735.0	-8.4	-0.1	2.8
<u>Temperature Salinity Conductivity</u>						
0.0	0.0	0.0				

The gravity drift and shift are values that have been added to the raw gravity to make up for drift in the meter that has been lost in accordance with a gravity check at each port stop.

Temperature, Salinity and Conductivity will only be valid while logging a Thermosalinograph, which is not usually the case.

Magnetics Data

mg.n

- A minus sign in the time stamp is flagged as a spike point, probably noise...
- Anomaly is based on the International Geomagnetic Reference Field revision 2000

CPU Time Stamp	Latitude	Longitude	Raw Value	Anomaly
200+077:00:23:00.000	N 16 11.2918	W 59 47.8258	36752.2	-166.8

Navigation File

n

CPU Time Stamp	Latitude	Longitude	Used	Set	Drift
2000+074:00:03:00.000	N 13 6.2214	W 59 37.9399	gpl	0.0	0.0

Navigation Block

nb0

Navigation is a compendium of Ewing logged data at shot time. The shot position here is the shot position from the Spectra system.

Shot Time	Shot #	CPU Time	Shot Position
2001+088:00:00:00.606	016967	2001+088:00:00:03.031	N 30 11.8324 W 042 10.8162

Water	Sea	Wind	-----	Tailbuoy	-----	Line				
Depth	Temp	Spd	Dir	Latitude	Longitude	Range	Bearg	Name	Speed	Heading
2565.1	20.7	16.4	164	N 30 12.0427	W 042 14.7319	6296.3	93.5	MEG-10	4.2	101.1

Tailbuoy Navigation

tbl.c

Raw tailbuoy fixes

CPU Time Stamp	Latitude	Longitude	GPS Precision
2001+088:00:00:02.000	N 30 12.0424	W 042 14.7309	SA

GPS Precision is either SA, DIFF or PCODE

Ewing Processed Shot Times

ts.n

Shot times and positions based on the Ewing navigation data processing

CPU Time Stamp	Shot #	Latitude	Longitude	Line Name
2000+079:00:08:01.507	000295	N 15 49.5703	W 060 19.7843	strikel

Shot Data Status

ts.n.status

The ts.nxxx.status file describes the line information for that day, giving some basic statistics about the line: start, end times; missing shots; start and end shots.

LINE strikel: 98+079:00:00:15.568 : 000283 .. 002286

MISSING: 347, 410, 1727

LINE dip2: 98+079:23:05:22.899 : 000002 .. 000151

This example says that on Julian Day 079 of 1998, two lines (strikel and dip2) were run: the end of strike 1 (shots 000283 to 002286) and the start of dip2 (shots 000002 to 000151).

Line strikel had some missing shots in the data file (probably missing on the SEG-d header as well).

Spectra Shot Times

nb2.r

The shot times and positions based on the Spectra positioning; with raw tailbuoy range and bearing.

CPU Time Stamp	Shot #	Latitude	Longitude	Line Name
2001+084:00:00:05.924	009245	N 23 31.2410	W 045 25.0894	

Latitude	Longitude	Tailbuoy Range	Bearing	Line Name
N 23 30.4540	W 045 21.4338	6389.8	283.2	KANE-4

Raw Gravity Counts

vc.r

sample BGM-3 gravity count record (without time tag):

pp:dddddd ss

			status: 00 = No DNV error; 01 = Platform DNV
			02 = Sensor DNV; 03 = Both DNV's
			count typically 025000 or 250000
			counting interval, 01 or 10

The input of data can be at 1 or 10 seconds.

Gravity Data

vt.n

- * A minus sign in the time stamp is flagged as a spike point
- * m_grv3 calculates the Eotvos correction as:
$$\text{eotvos_corr} = 7.5038 * \text{vel_east} * \cos(\text{lat}) + .004154 * \text{vel} * \text{vel}$$
- * The theoretical gravity value is based upon different models for the earth's shape.
 - 1930 = 1930 International Gravity Formula
 - 1967 = 1967 Geodetic Reference System Formula
 - 1980 = 1980 Gravity Formula
- * The FAA is computed as:
$$\text{faa} = \text{corrected_grv} - \text{theoretical_grv}$$
- * Velocity smoothing is performed w/ a 5 point window

CPU Time Stamp	Latitude	Longitude	Model	FAA	RAW
2000+148:00:10:00.000	N 09 34.7255	W 085 38.5826	1980	9.48	978264.16

Eotvos	Drift DC	Raw Velocity	Smooth Velocity			
Smooth	Total Shift	North	East	North	East	
-74.78	0.06	4.16	1.875	-10.373	1.927	\10.166

Datum Time

ts2.r

CPU Time	Datum Time	Time Reference
2001+069:00:15:29.727	069 00 15 29.378	datum

Raw GPS

gp(12).d, tb1.d

Raw GPS is in NMEA Format.

Meteorological Data

WX

```

                                True
CPU Time Stamp      Spd Dir
2001+045:00:00:00.967  7.8 22

Bird1:
Speed              Direction
Inst 60sA 60mA 60sM Inst 60sA 60mA
7.8  6.6  8.5  16.8 277 291 5

Bird 2
Speed              Direction
Inst 60sA 60mA 60sM Inst 60sA 60mA
0.0  0.0  0.0  0.0  0  0  0

Temperature
Inst 60mA 60mm 60mM
15.0 14.2 14.3 15.1

Humidity
Inst 60mm 60mM
92  90  93

Barometer
1027.5

Inst:      Current
60sA:      60 second average
60mA:      60 minute average
60sM:      60 second maximum
60mm:      60 minute minimum
60mM:      60 minute maximum
```

Merged Meteorological Data

mmet

```

TSG, WX, CT merged with Nav at 1 minute fixes
date      time      lat      lon      gpu head spd
2001+244:00:00:00.000 12.14071 44.98469 gp1 10.2 83.0
```

```

twS twd temp hum press cti cte con sal ct
26.5 228.0 30.6 87.0 1000.8 28.8 28.8 5.9 36.3 28.8
```

```

gpu  = gps unit in use
head = ship's heading
spd  = ship's speed in knots
twS  = true wind speed
twd  = true wind direction
temp = air temp (celcius)
hum  = relative humidity (%)
press= pressure in mb
cti  = sea temp from the internal TSG sensor
cte  = sea temp from the external TSG sensor
con  = conductivity, Siemens/meter
sal  = salinity, practical salinity units
ct   = sea temp from the C-keel sensor (to tenths of a degree)
```

Tape Contents

EW0310/

CruiseReport_EW0310.pdf	This document
ew0310.cdf	NetCDF database file of this cruise
ew0310.cdf_nav	NetCDF database file of this cruise' navigation
XBT/	XBT data
spectra/	Spectra P1/P2 files and configs
configs/	logging and reduction configs
sodar/	3.5kHz digital data
waypoints/	waypoint spreadsheets and text files
docs/	File Formats, UKOOA Formats
processed/	Processed datafiles merged with navigation
shotlogs/	processed Shot Files
trackplots/	daily cruise track plots (<i>postscript</i>)
raw/	Raw data directly from logger
reduction/	Reduced data files
clean/	daily processing directory, includes daily
postscript plots of the data	
scripts/	Perl scripts and their friends
MMO/	Marine Mammal Observations
waypoints/	Waypoints working directory